

Forum des Microscopies à Sondes Locales – 18 mars 2019

AFM et mécanobiologie

Vincent Dupres

Institut Pasteur

CNRS – INSERM – Univ. Lille

Cellular Microbiology and Physics of Infection

<http://www.cmpi.cnrs.fr>

vincent.dupres@ibl.cnrs.fr



Mechanobiology

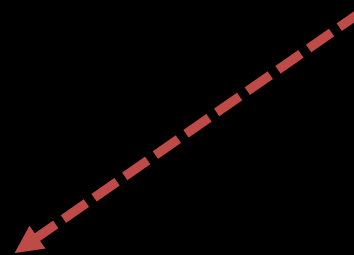
How cells could sense and respond to the physical properties of their environment ?

→ dependent on dynamic subcellular systems that can generate and transduce mechanical force.

Cellular function modification
(biochemical processes or diseases)

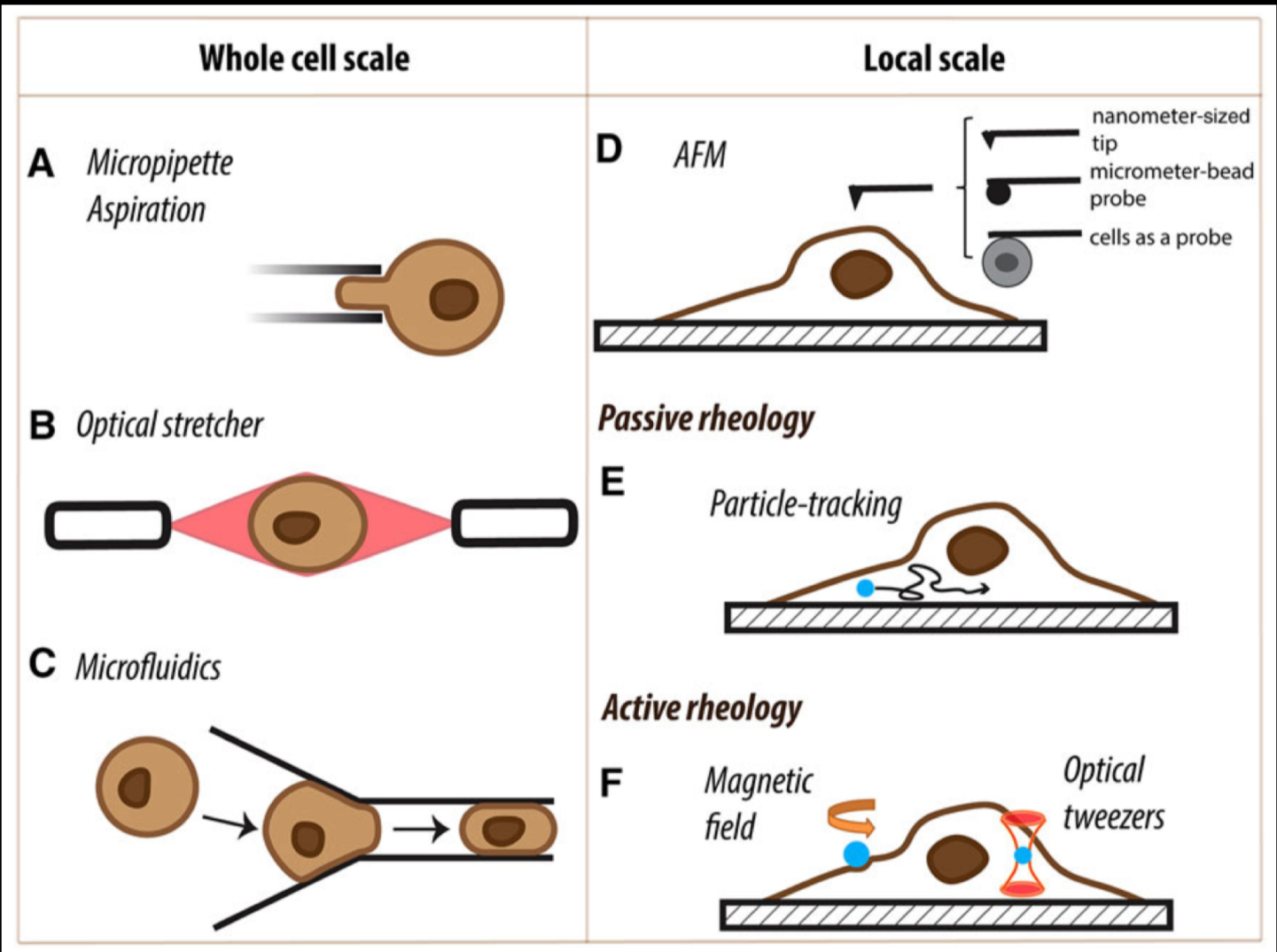


Mechanical properties



indicator of their biological status

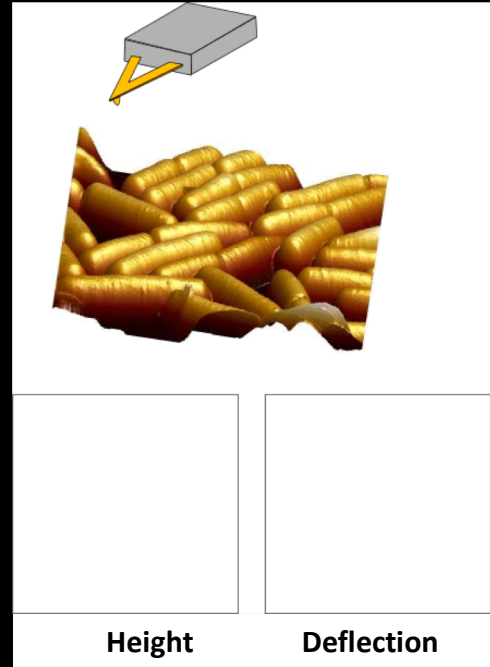
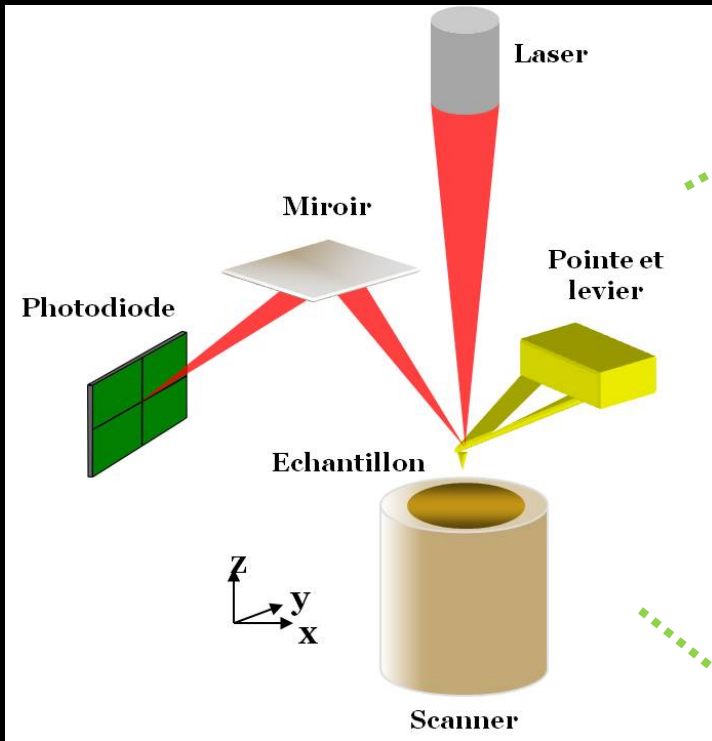
Mechanobiology



- 1) How can we measure cell mechanics by AFM ?
- 2) Why (cell mechanics in diseases) ?
- 3) Perspectives

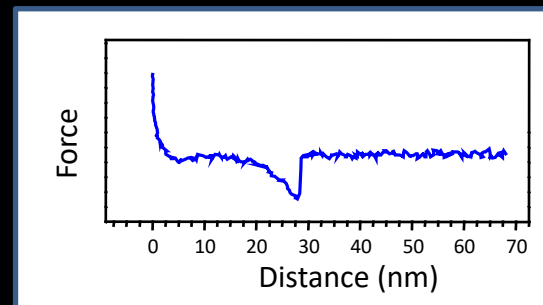
Atomic Force Microscopy : principle

• Imaging



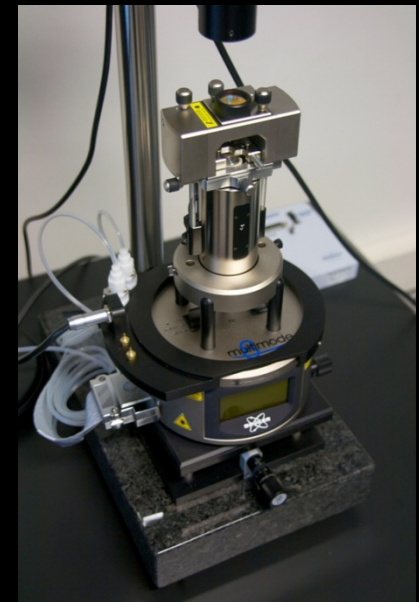
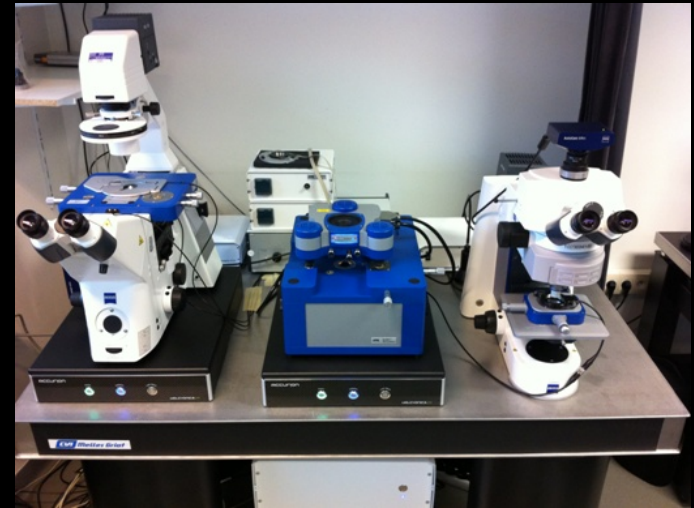
- resolution : nm
- minimal sample prep
- in buffer
- ~ real time

• Force spectroscopy

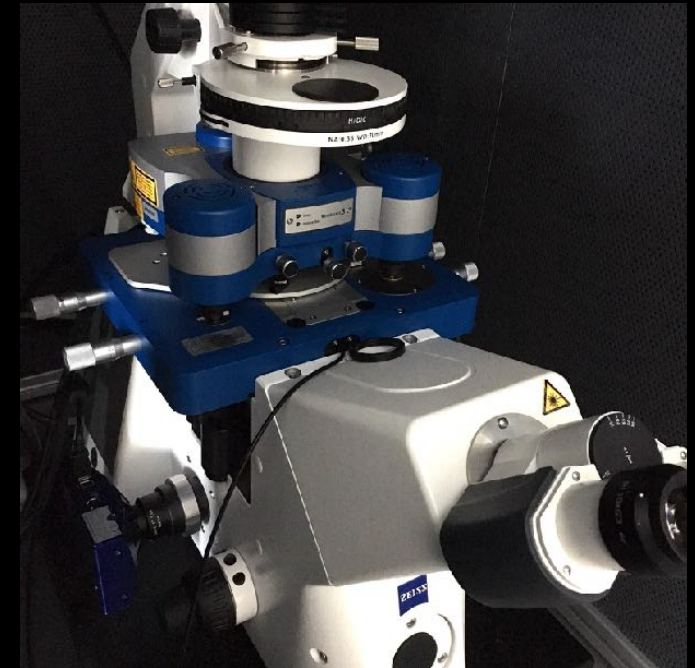
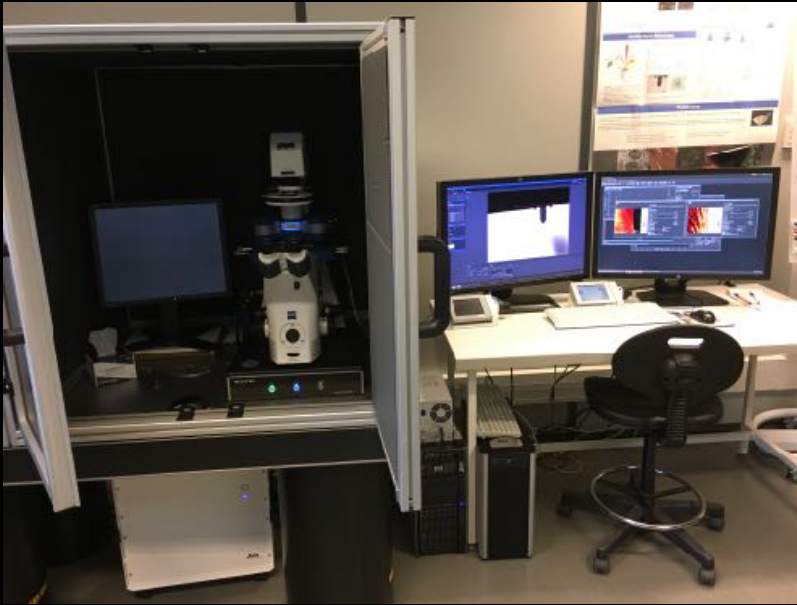


- pN sensitivity
- single molecule
- Physical properties
- cartography

Different models for different applications



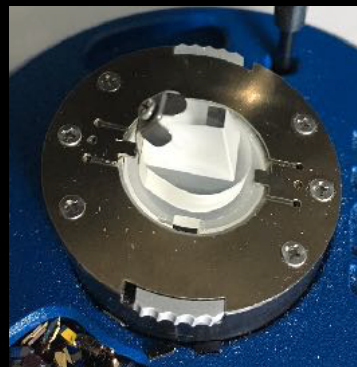
JPK NanoWizard III AFM



AFM scanning head (xyz) and stage (z)



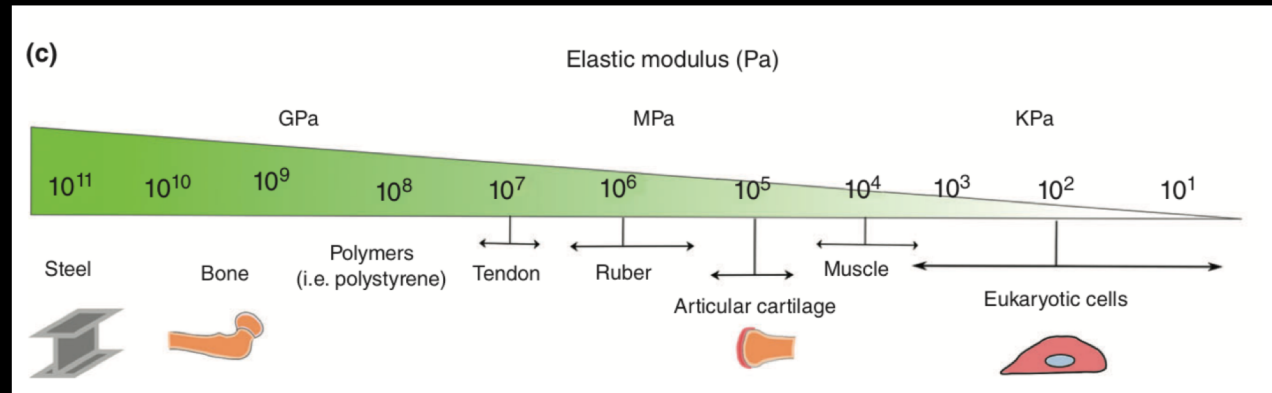
Petri dish heater



Cantilever holder

Choice of the probe

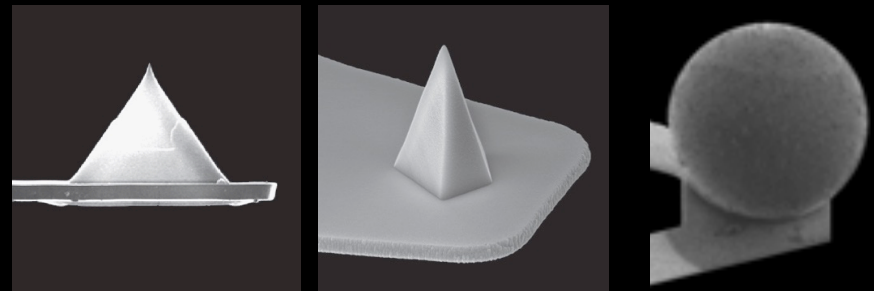
→ Stiffness of the cantilever (spring constant k)



→ Tip shape

tip radius : 2-500 nm

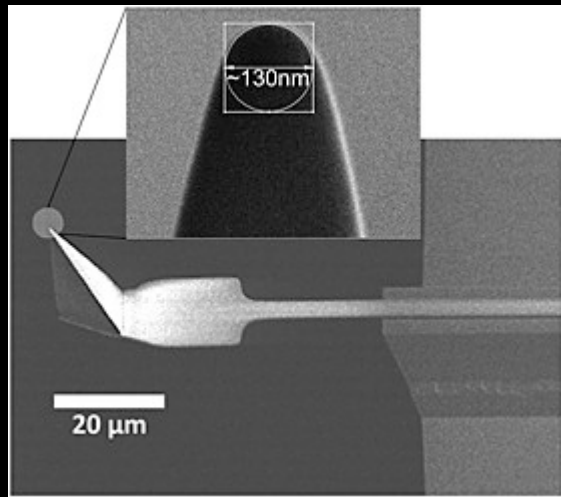
tip height : 3-20 μm



Choice of the probe

Long tips enabling imaging of cell surfaces even with large height differences

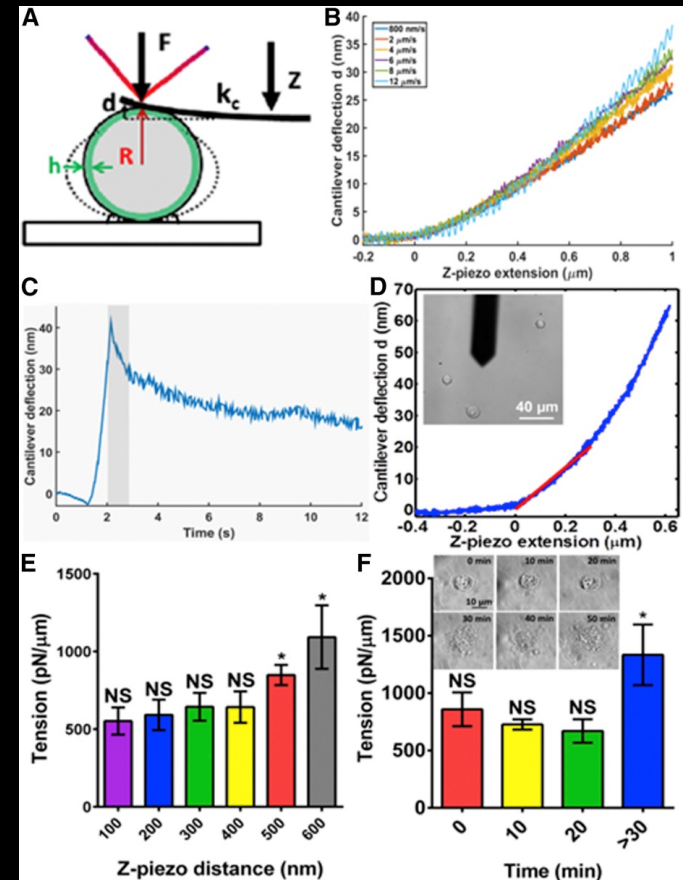
→ PeakForce QNM-Live Cell probe



Schillers *et al.*, J. Mol. Rec., 2016

→ short cantilever with a $17\text{-}\mu\text{m}$ -long tip (minimizes hydrodynamic effects between the cantilever and the sample surface)

Tipless cantilever



Cartagena-Rivera, Biophys.J, 2016

Calibration

Force measurements in practice : calibration of force distance curves

Cantilever : Hookean spring

$$F = k \times d$$

→ Sensitivity (of the optical detection system)

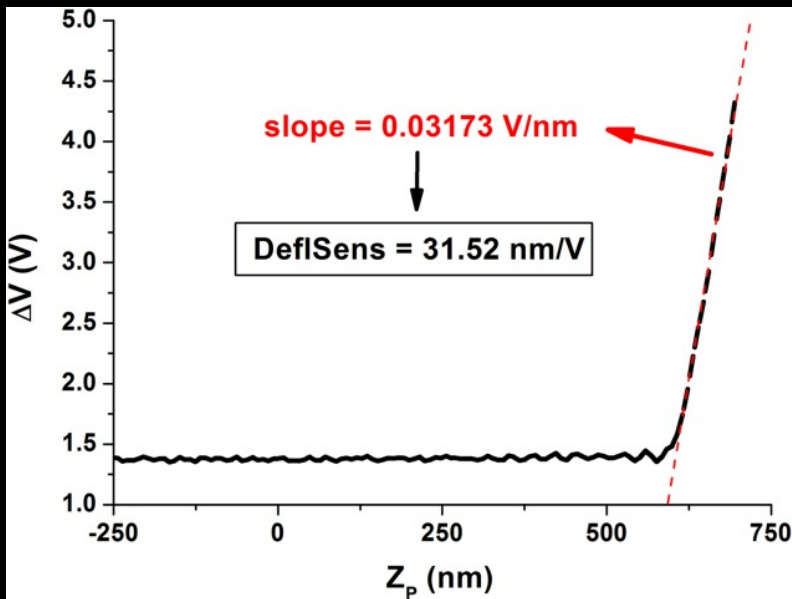
→ Cantilever spring constant k

Calibration

Deflection sensitivity (nm/V)

- voltage signal detected by the photodiode (V)
- conversion factor : $V \rightarrow \text{nm}$

OLS (optical lever sensitivity)



→ calculated from the slope in a force-distance curve obtained on a hard substrate (such as glass)

⇒ InvOLS : nm/V

Calibration

Cantilever stiffness : spring constant (k)

→ Nominal ~~stiffness~~

→ Sader method

→ Thermal fluctuations method

Equipartition theorem

$$\frac{1}{2} k_B T = \frac{1}{2} k \langle \Delta x^2 \rangle$$

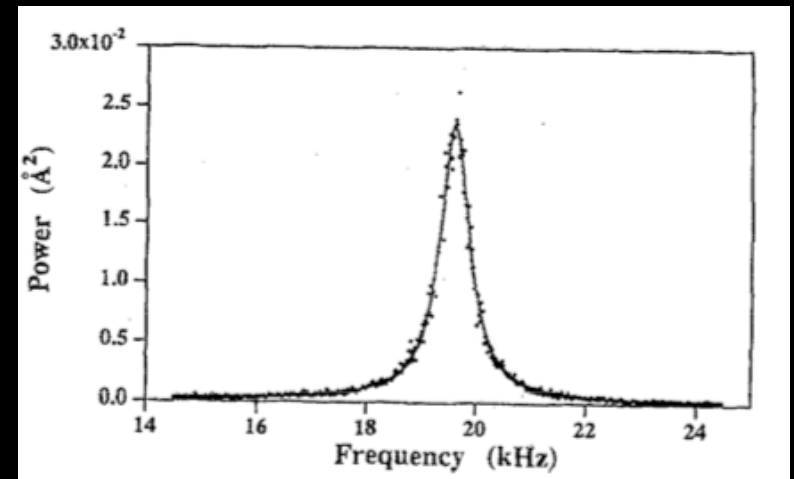
k : spring constant

k_B : Boltzmann constant

T : temperature (K)

$\langle \Delta x^2 \rangle$: thermal noise

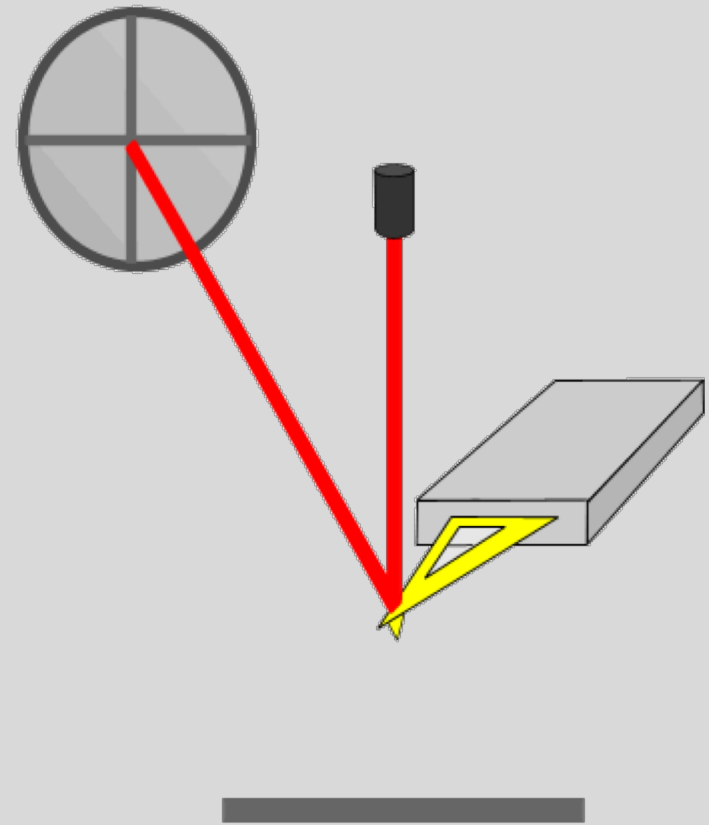
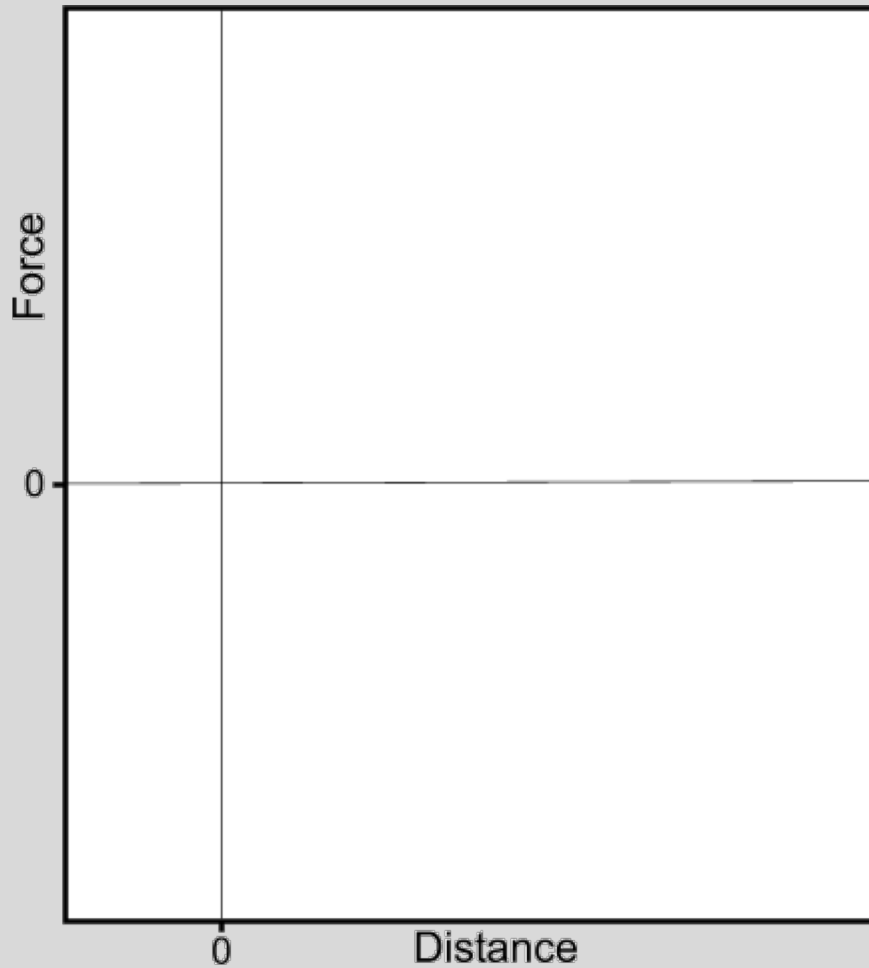
→ power spectrum



To be carried out at each cantilever change and after each laser adjustment

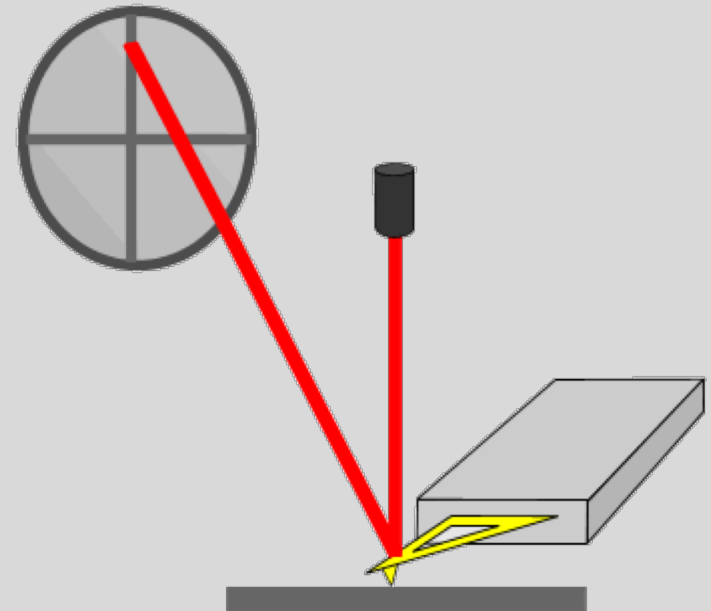
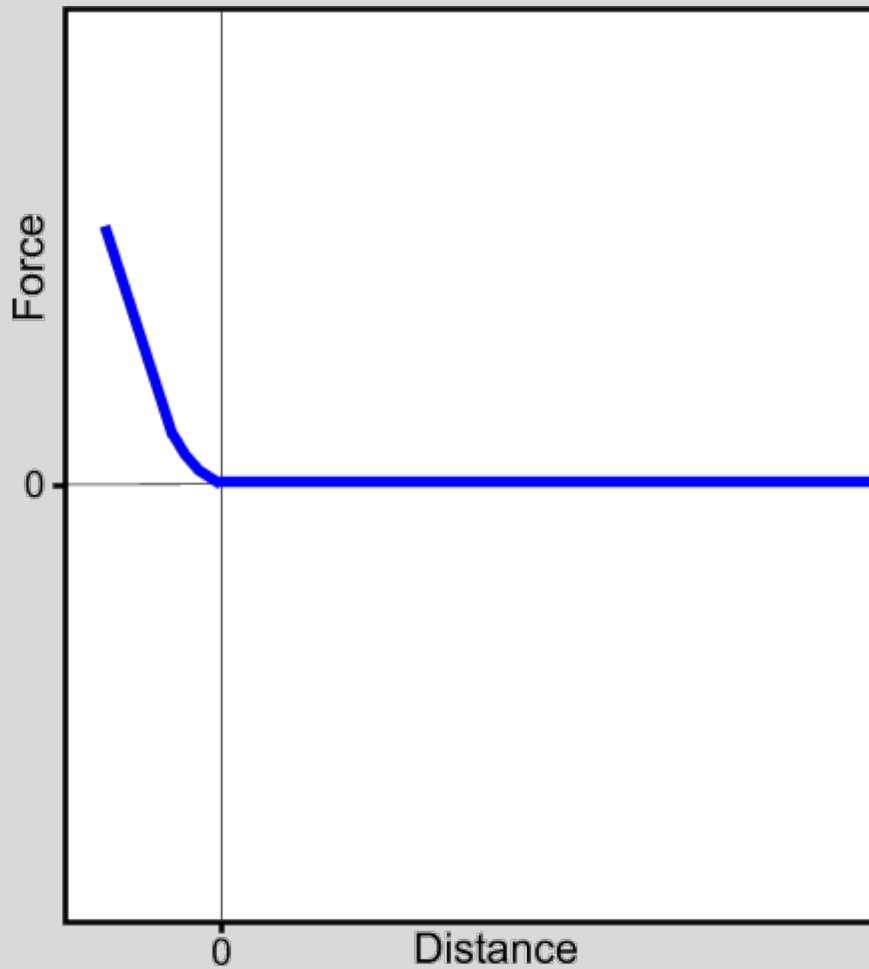
Force spectroscopy

→ Force-distance curve (approach)



Force spectroscopy

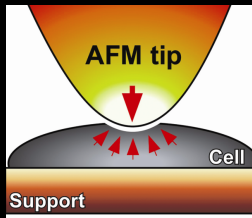
→ Force-distance curve (retract)



Force spectroscopy

One force-curve : two different parts

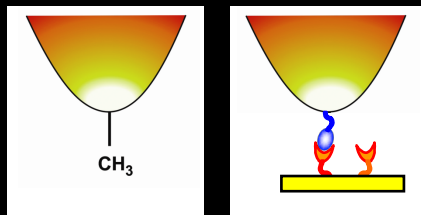
Approach curve
⇒ **mechanical properties**



Elasticity (Young's modulus)

Viscosity (visco-elasticity)

Retract curve
⇒ **physico-chemical properties**



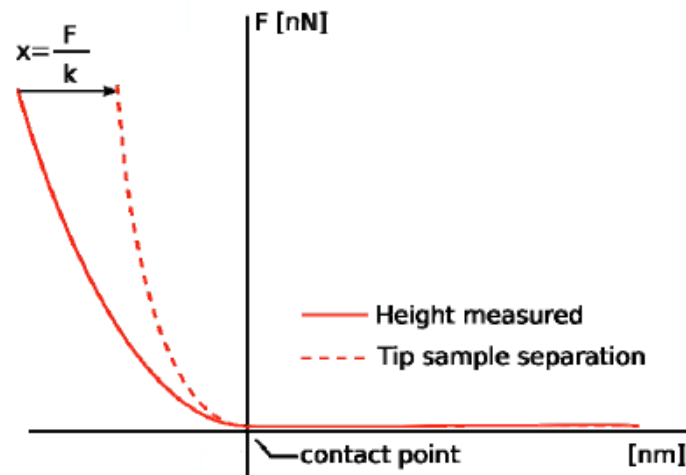
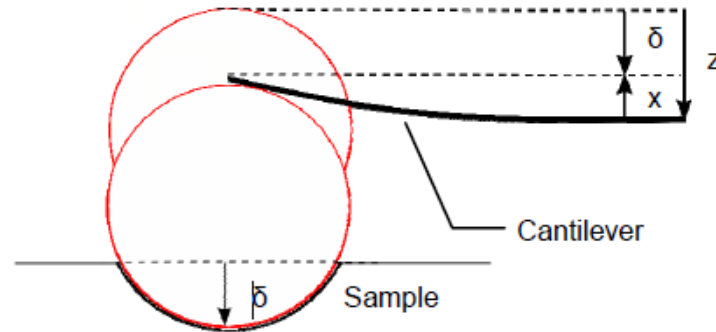
Single mol. manipulation (unfolding)

Hydrophobicity (CFM)

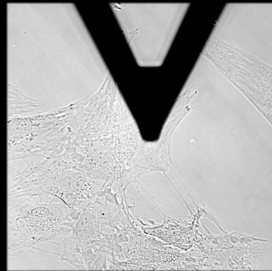
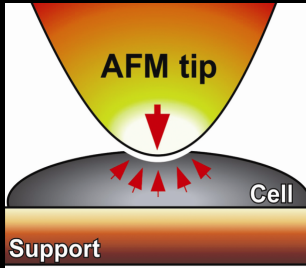
**Molecular recognition imaging
(adhesion maps)**

**Polymer conformational analysis
(elasticity, length)**

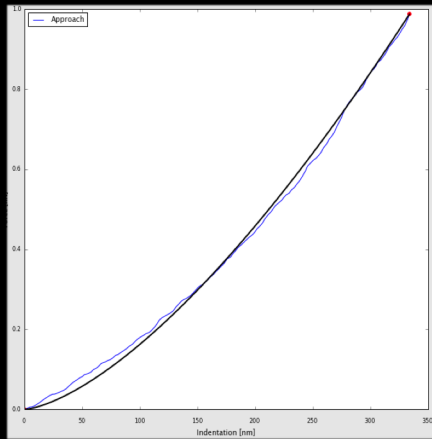
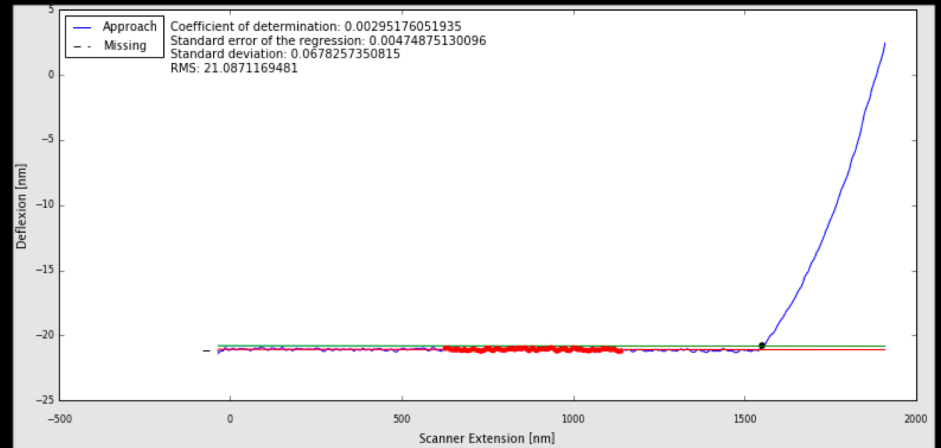
Mechanical properties : Young modulus



Mechanical properties : Young modulus



Force vs indentation curves



Hertz model

$$F = \frac{4}{3} \frac{E}{1-\nu^2} \sqrt{R\delta^3}$$

F : applied force

R : radius of the probe

δ : indentation

E : elastic modulus

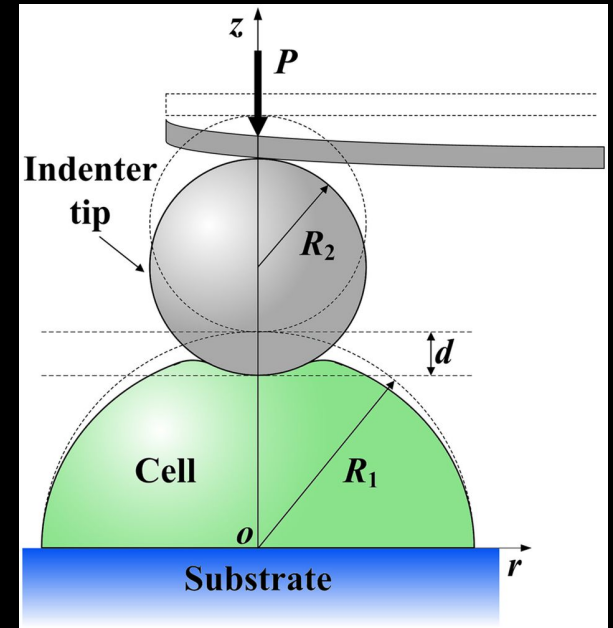
ν : Poisson's ratio

Young's modulus → cell elastic properties

Mechanical properties : Hertz Model

H. Hertz, Über die Berührung fester elastischer Körper, Journal für die reine und angewandte Mathematik 92, 156-171 (1881)

→ Two elastic, deformable spheres

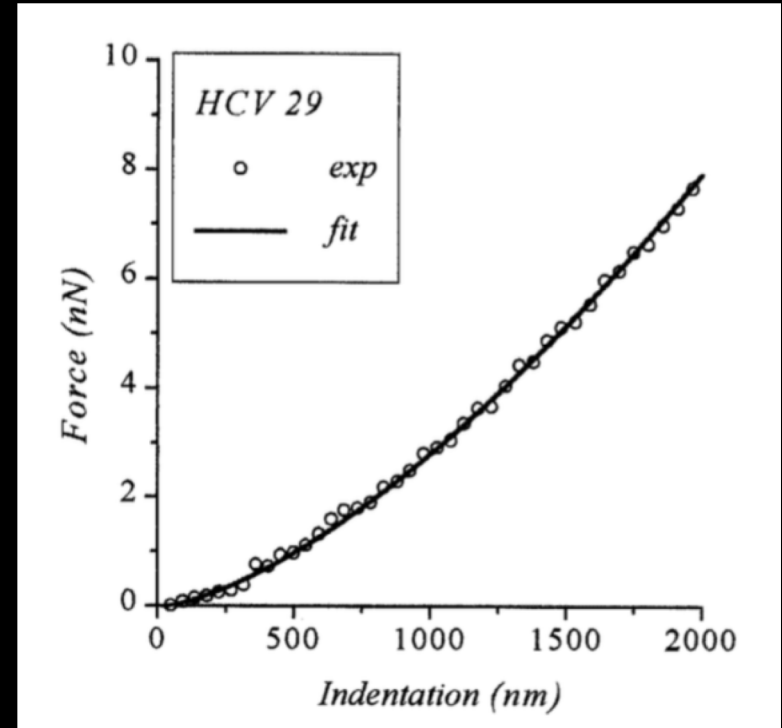
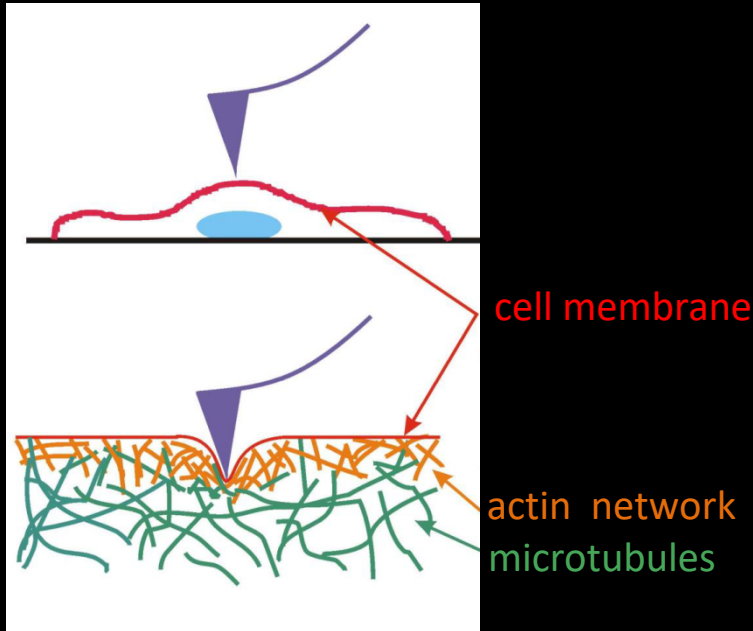


Assumptions of the Hertz theory :

- Homogeneous and isotropic material
- Linear elastic material properties
- Non-adhesive tip-sample contact
- Infinite sample thickness
- Small stresses (infinitesimal deformations)

Mechanical properties : Hertz Model

But cells are heterogeneous...

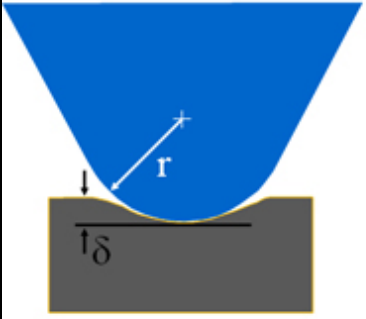


Lekka *et al.*, Eur Biophys J (1999)

→ The Hertz fit works surprisingly well...

Mechanical properties : Hertz Model

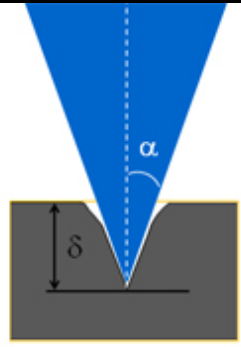
There are variants of the Hertz model for different probe geometries



E_s : Sample modulus
 ν_s : Poisson's ratio
 r : tip radius of curvature
 α : opening angle

$$F = \frac{4}{3} \cdot \frac{E_s}{1 - \nu_s^2} \cdot \sqrt{r} \cdot \delta^{\frac{3}{2}}$$

Hertz Model



$$F = \frac{2}{\pi} \cdot \frac{E_s}{1 - \nu_s^2} \cdot \tan \alpha \cdot \delta^2$$

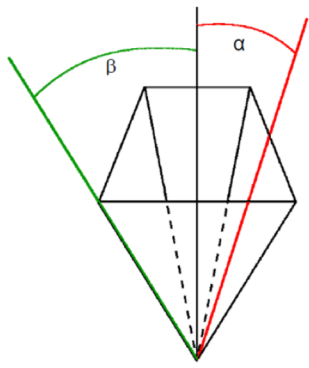
Sneddon Model

Four-sided pyramid

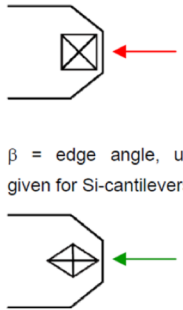
$$F = \frac{E}{1 - \nu^2} \frac{\tan \alpha}{\sqrt{2}} \delta^2$$

$$a = \frac{\tan \alpha}{\sqrt{2}} \delta$$

α = face angle, usually given for Si_3N_4 -cantilevers

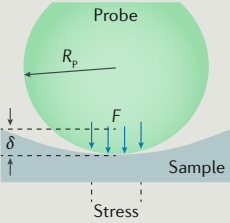
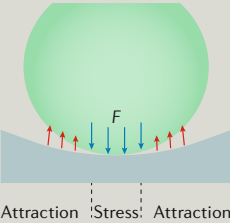
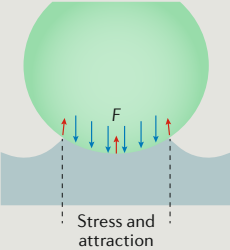


β = edge angle, usually given for Si-cantilevers



JPK, Application Note

<http://www.iupui.edu/~bbml/>

Model	Probe geometry	Force	Additional assumptions	Schematic representation
Hertz	Spherical	$F = E_{\text{eff}} \cdot \left[(a^2 + R_p^2) \cdot \ln \left(\frac{R_p + a}{R_p - a} \right) - 2aR_p \right]$ $\delta = \frac{a}{2} \ln \frac{R_p + a}{R_p - a}$	No surface forces	
	Cylindrical	$F(\delta) = 2E_{\text{eff}} \cdot R_z \delta$	Smooth punch profile (no edges)	–
	Conical (Sneddon model)	$F(\delta) = E_{\text{eff}} \cdot 2 \tan(\theta) / \pi \cdot \delta^2$	Infinitely sharp probe	–
	Parabolic	$F(\delta) = E_{\text{eff}} \cdot \frac{4\sqrt{R_p}}{3} \delta^{\frac{3}{2}}$	$R_c > \delta$	–
Blunted pyramidal		$F(\delta) = 2E_{\text{eff}} \cdot \left[\delta a - \frac{\sqrt{2}}{\pi} \frac{a^2}{\tan\theta} \left(\frac{\pi}{2} - \arcsin \frac{b}{a} \right) - \frac{a^3}{3R_p} + \sqrt{(a^2 - b^2)} \cdot \left(\frac{\sqrt{2}}{\pi} \frac{b}{\tan\theta} + \frac{a^2 - b^2}{3R_p} \right) \right]$	Cross section of pyramid modelled as a circle	–
Derjaguin–Müller–Toporov	Spherical	$F = F_{\text{Hertz}} - F_{\text{det}}$ $\delta = \frac{a}{2} \ln \frac{R_p + a}{R_p - a}$	<ul style="list-style-type: none"> • Long-range surface forces outside the contact area • Valid for stiff materials, small spheres and weak adhesion 	
Johnson–Kendall–Roberts	Spherical approximated with a paraboloid	$F = F_{\text{Hertz}} - 4\sqrt{\frac{E_{\text{eff}} \cdot F_{\text{det}} a^3}{3R_p}}$ $\delta = \frac{a^2}{R_p} - 2\sqrt{\frac{F_{\text{det}} \cdot a}{3E_{\text{eff}} R_p}}$	<ul style="list-style-type: none"> • Short-range surface forces inside the contact area • Valid for compliant materials, large spheres and strong adhesion 	
Non-Hertzian contact models				
Cortical shell liquid core	Spherical	$F = \left[2T_c \left(\frac{1}{R_c} + \frac{1}{R_p} \right) \cdot 2\pi R_p \right] \cdot \delta$	<ul style="list-style-type: none"> • Linear force–displacement curves; large membrane reservoir • Variable: T_c 	–
Standard linear solid	Conical, spherical	Analytical ¹⁷⁵ and numerical ¹⁷⁷ expressions	<ul style="list-style-type: none"> • Time-varying elastic modulus • Variable: viscosity 	–
Poroelastic	Spherical	$F \approx e^{-D_p \cdot t R_p \cdot \delta}$	<ul style="list-style-type: none"> • Constant volume; timescale < 0.5 s • Variable: $D_p \approx E\xi^2/\eta$ 	–
Thin shell	Conical	$F \approx \delta \cdot E \cdot h^2 / R_s$	<ul style="list-style-type: none"> • Point probe; $h \ll R_s$ • Variables: R_s and h 	–

Influence of the substrate

Hertz model : infinite sample thickness (neglectable indentation)

→ **BEC model (Bottom Effect Correction)**

(Take into account the mechanical contribution of the stiff substrate)

- **Bead (spherical tips)**

$$E = \frac{9F}{16} \frac{1}{R^{1/2} \delta^{3/2}} \frac{1}{\left(1 + 1.133\chi + 1.283\chi^2 + 0.769\chi^3 + 0.0975\chi^4\right)}$$

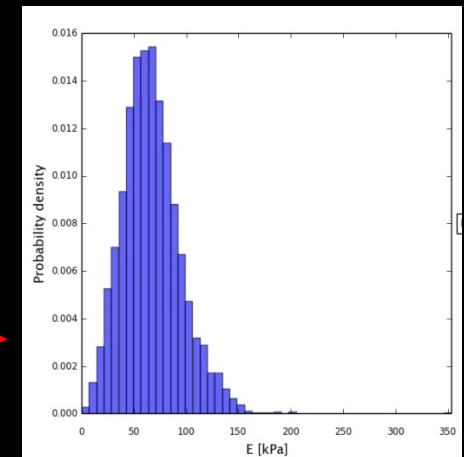
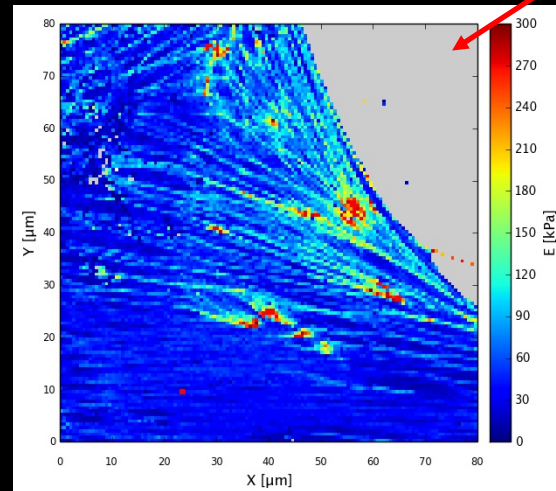
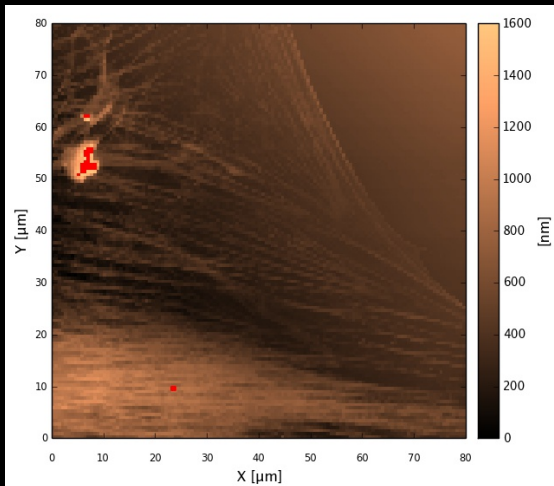
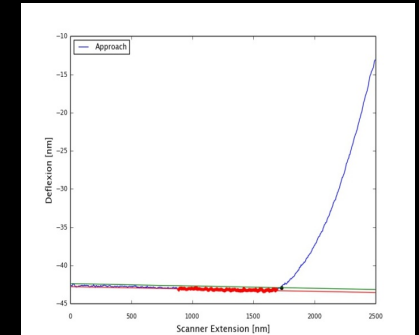
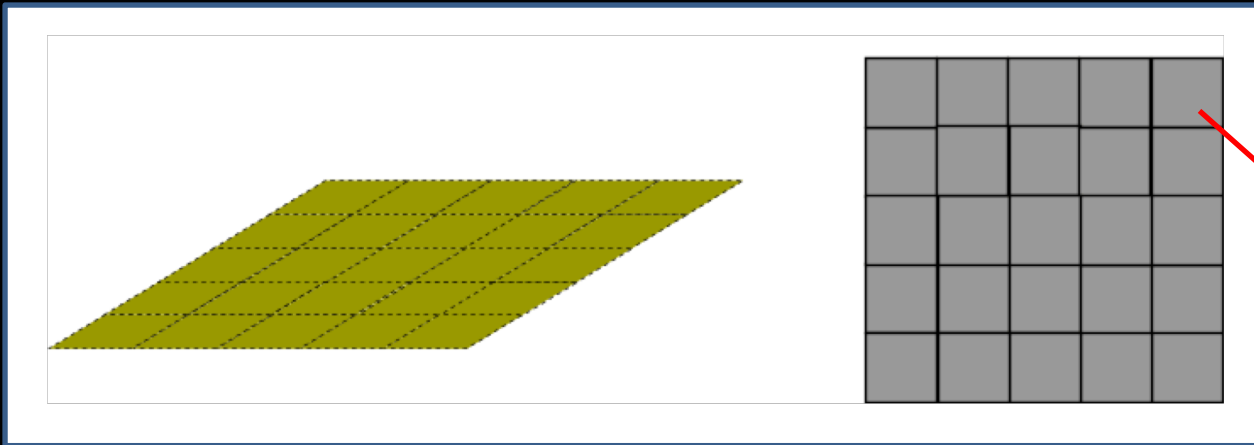
Dimitriadis et al., *Biophys J*, 2002

- **Cone shaped tips**

$$F = \frac{8E \tan \theta \delta^2}{3\pi} x \left\{ 1 + 1.7795 \frac{2 \tan \theta}{\pi^2} \frac{\delta}{h} + 16(1.7795)^2 \tan^2 \theta \frac{\delta^2}{h^2} + O\left(\frac{\delta^3}{h^3}\right) \right\}$$

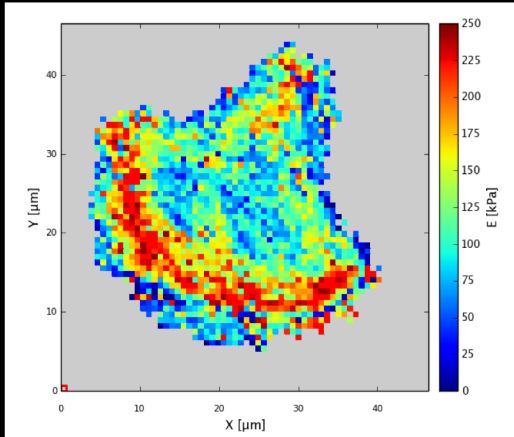
Gavara & Chadwick, *Nature Nanotech*, 2012

Mechanical properties : elasticity maps

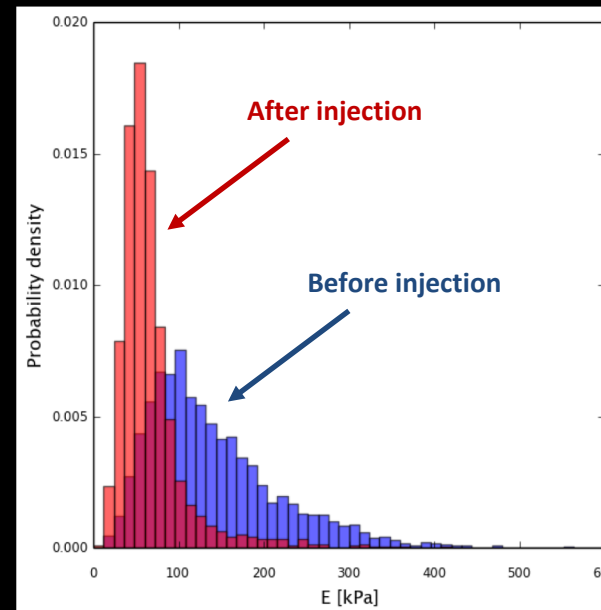
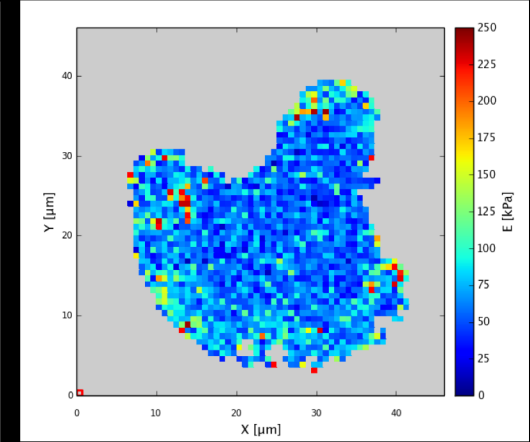
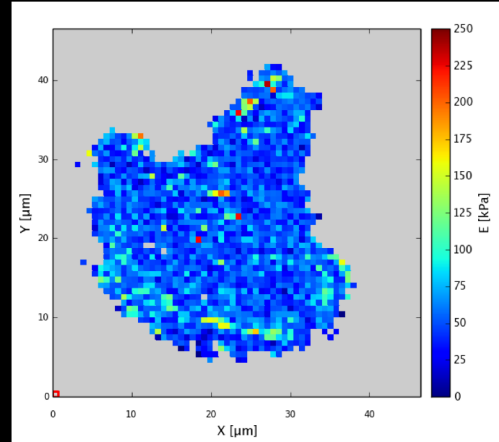


Mechanical properties : elasticity maps

After injection of latrunculin A (0.2 μ M)



RPE1 cells

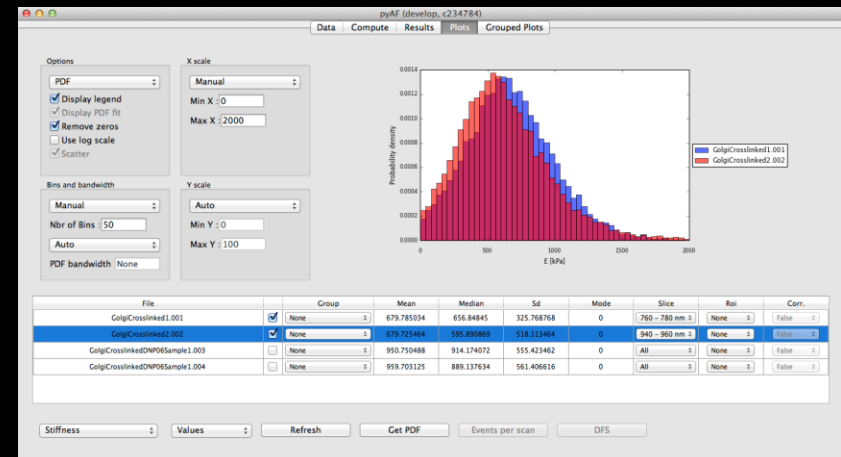
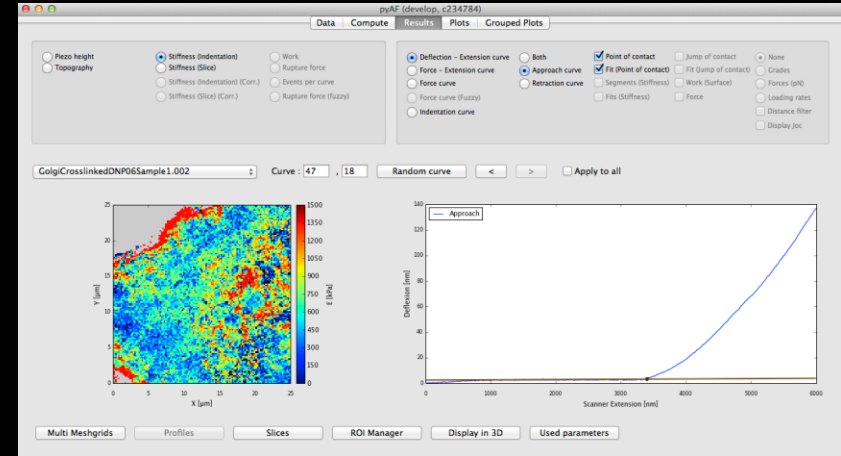
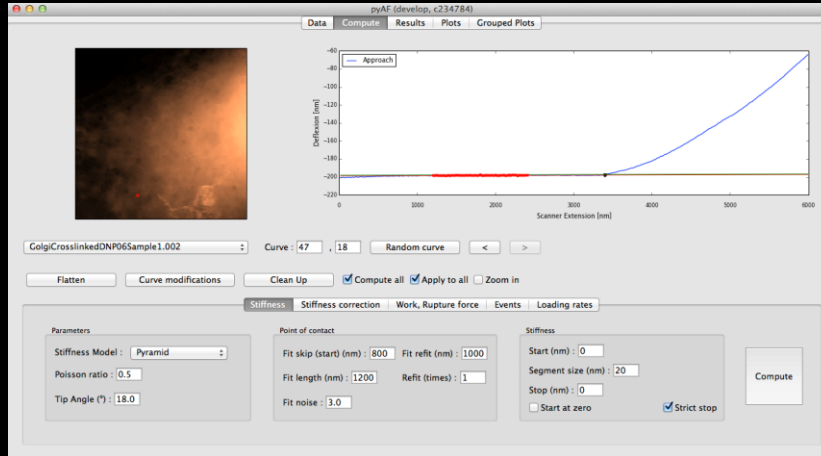


Analysis

manual vs auto → home-built software

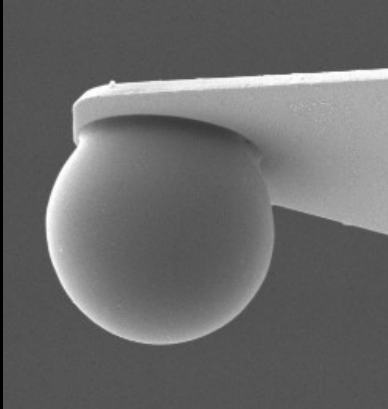
pyAF

Elasticity mapping



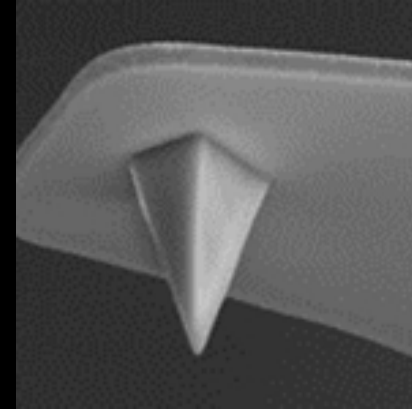
Histograms (stats)

Sharp tips or colloidal probes



Colloidal probes :

- Whole cell elasticity
- Well defined geometry
- Large contact area

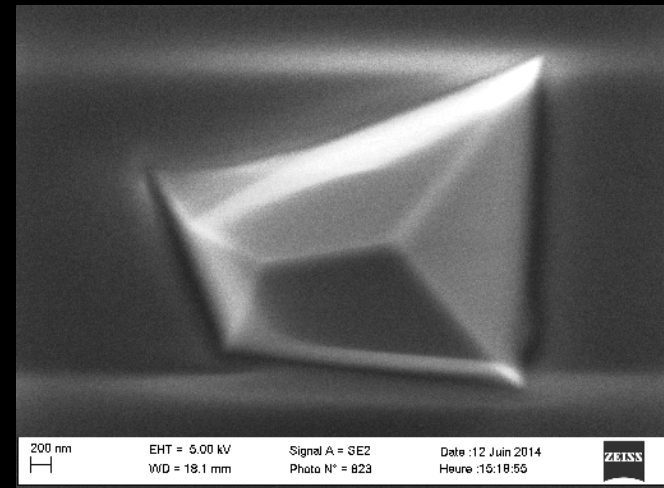
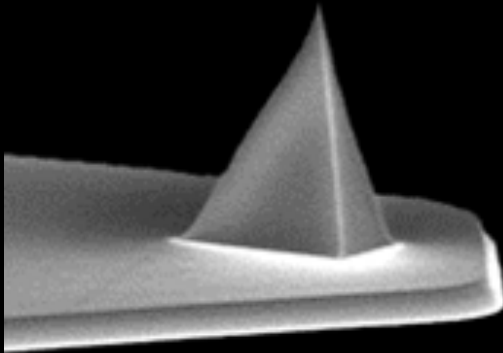


Sharp tip :

- Force mapping
- Precise tip geometry unclear
- Strain stiffening
- Damage a cell at high LR

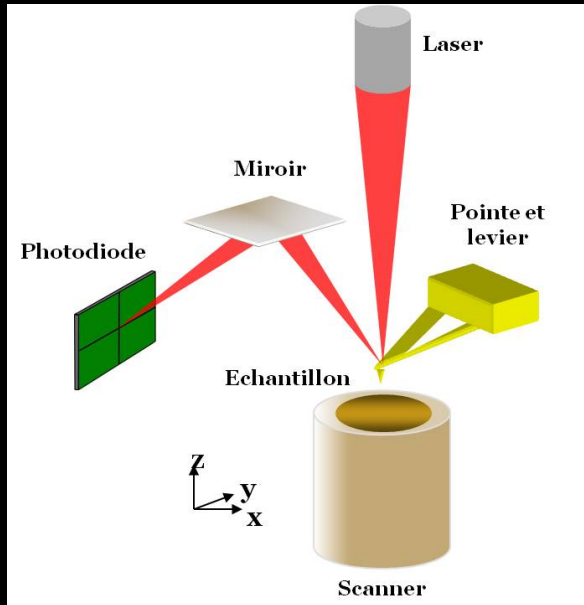
Limitations : Elasticity measurements

- **Models in function of the tip geometry (Force, contact area ...)**
- **Determination of the shear modulus**
- **Determination of the viscous drag**
- **Determination of the hydrodynamic drag on the cantilever**
- **Quality of the probe**



Sources of errors

Determination of deflection sensitivity is a critical step in cantilever calibration



position of the laser spot on the detector (V)



z-piezo movement (nm)

(how much cantilever bending corresponds to 1 V detector signal)

→ Deflection sensitivity (nm/V)

⇒ a small variation of the deflection sensitivity value causes a significant change in spring constant k (and then the calculated force F)

→ SNAP protocol (2017)

SCIENTIFIC REPORTS





OPEN

Standardized Nanomechanical Atomic Force Microscopy Procedure (SNAP) for Measuring Soft and Biological Samples

Received: 10 January 2017

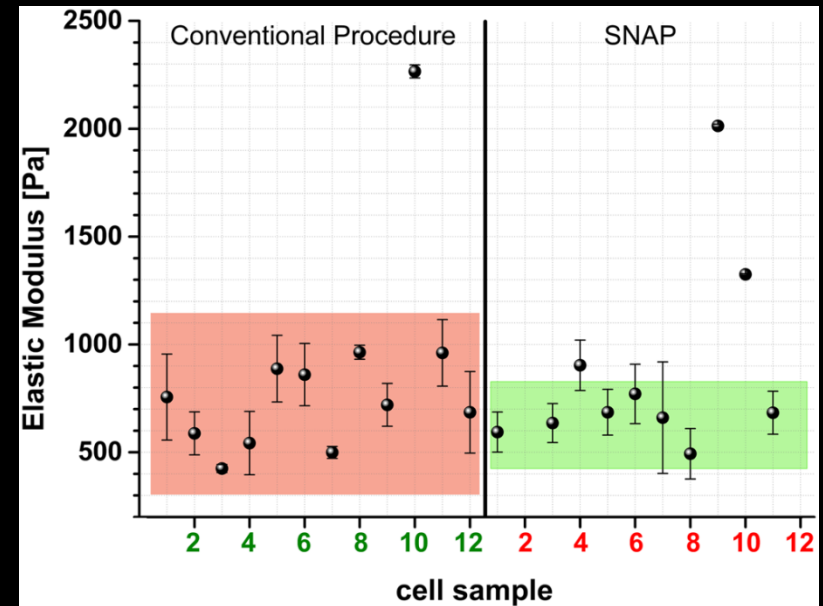
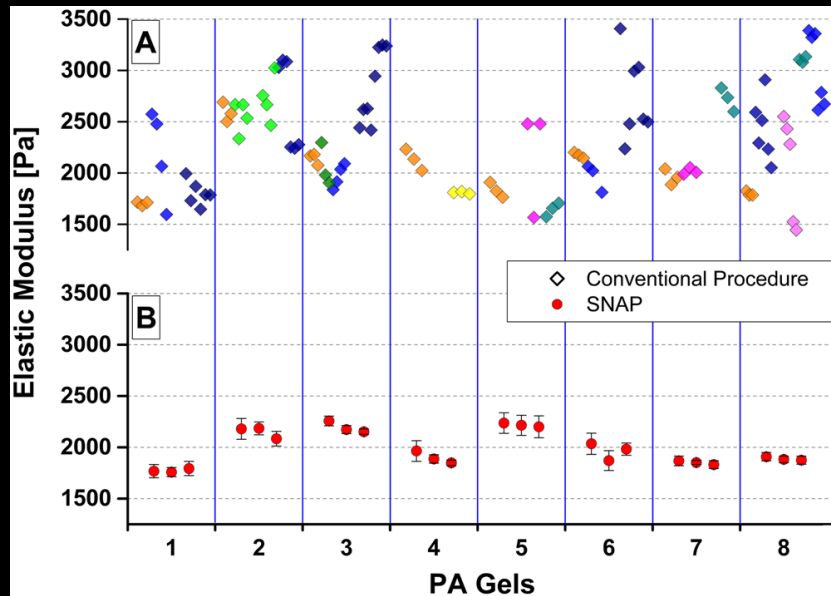
Accepted: 26 May 2017

Published online: 11 July 2017

Hermann Schillers¹, Carmela Rianna², Jens Schäpe², Tomas Luque³, Holger Doschke², Mike Wälte¹, Juan José Uriarte³, Noelia Campillo³, Georgios P. A. Michanetzis⁴, Justyna Bobrowska⁵, Andra Dumitru⁶, Elena T. Herruzo⁶, Simone Bovio⁷, Pierre Parot^{8,9}, Massimiliano Galluzzi^{10,11,12}, Alessandro Podestà ¹⁰, Luca Puricelli¹⁰, Simon Scheuring^{13,14,15}, Yannis Missirlis⁴, Ricardo Garcia⁶, Michael Odorico^{9,16}, Jean-Marie Teulon^{9,17}, Frank Lafont ⁷, Malgorzata Lekka⁵, Felix Rico ¹³, Annafrancesca Rigato¹³, Jean-Luc Pellequer^{9,17}, Hans Oberleithner¹, Daniel Navajas³ & Manfred Radmacher ²

SNAP procedure

- Calibrated cantilever (known $k \leftrightarrow$ interferometer)
- Thermal
- Deflection sensitivity



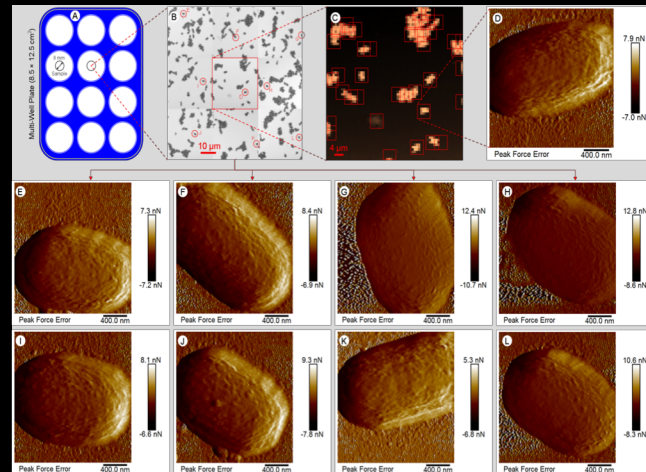
⇒ the errors present in gel measurements decreased from 30% down to 1% while in cell measurements the consistency increased by a factor of 2.

Statistics

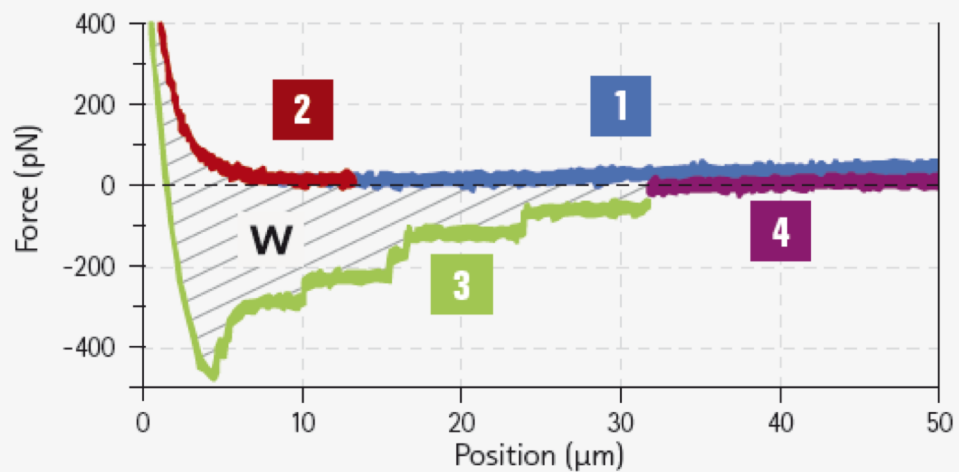
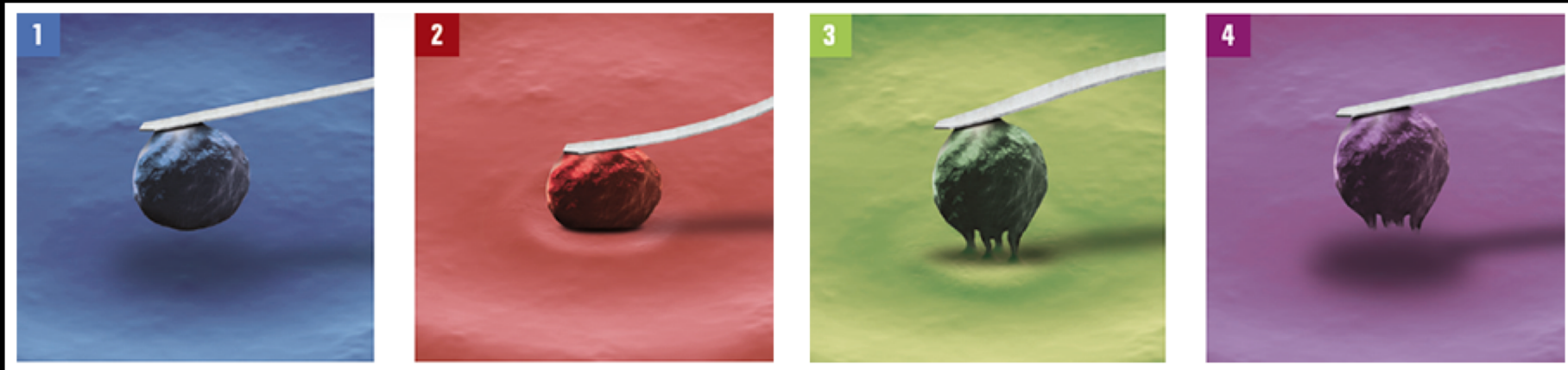
	Colloidal probe	Sharp tip (mapping)
Cells per condition (sample)	~ 50-100	~ 10-20
Force curves recorded per single cell	~ 1-10	~ 100-10000

⇒ Several thousand of force curves to be analyzed

→ Fully automated multi-sample analysis using AFM



Cell Hesion (JPK)



Summary

Working conditions for a cell mechanics experiment :

- stiffness of the cantilever (k)
- shape of the indenting tip (\Rightarrow model)
- location on the cellular surface (whole cell, nucleus, ...)
- fix all the parameters :
 - ✓ setpoint (indenting force / depth)
 - ✓ tip velocity (ramp, frequency, ...)

For best results in mechanical measurements :

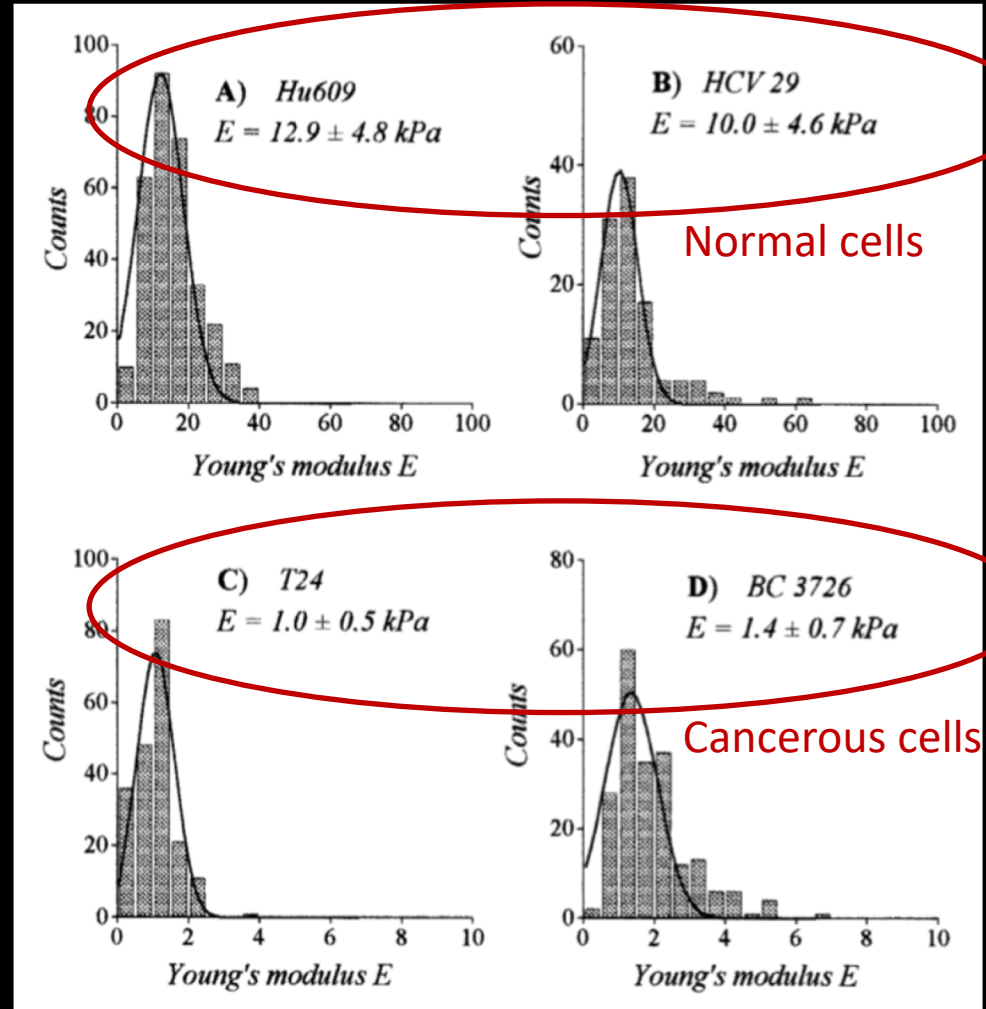
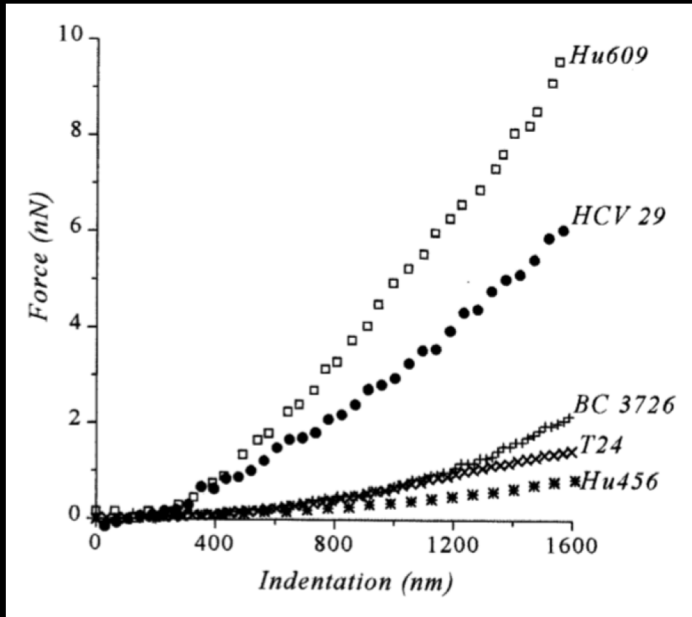
- use colloidal probes
- spring constant calibrated by an interferometer
- set the deflection sensitivity according to the SNAP procedure
- if possible, use the same cantilever...

\Rightarrow Absolute values of the Young's modulus are difficult to be obtained

- 1) How can we measure cell mechanics by AFM ?
- 2) Why (cell mechanics in diseases) ?
- 3) Perspectives

Relevance in Medicine and Physiology

→ Cell stiffness changes during cancer





ELSEVIER

Contents lists available at SciVerse ScienceDirect

Micron

journal homepage: www.elsevier.com/locate/micron



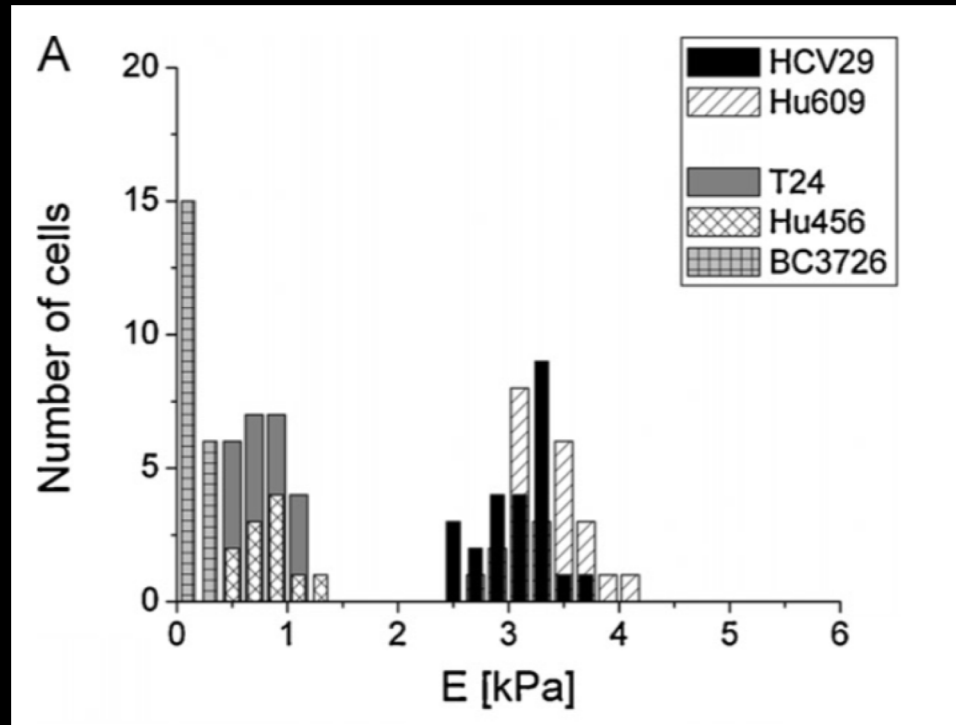
Cancer cell recognition – Mechanical phenotype

Małgorzata Lekka^{a,*}, Katarzyna Pogoda^a, Justyna Gostek^{a,b}, Olesya Klymenko^a,
Szymon Prauzner-Bechcicki^a, Joanna Wiltowska-Zuber^a, Justyna Jaczewska^{a,c},
Janusz Lekki^a, Zbigniew Stachura^a

^a The Henryk Niewodniczański Institute of Nuclear Physics, Polish Academy of Sciences, Radzikowskiego 152, 31-342 Kraków, Poland

^b The Marian Smoluchowski Institute of Physics, Jagiellonian University, Reymonta 4, 30-342 Kraków, Poland

^c Florida Atlantic University, Charles E. Schmidt College of Medicine, 777 Glades Rd., Boca Raton, FL 33431, United States



→ Cell stiffness changes during cancer (tissue)

nature
nanotechnology

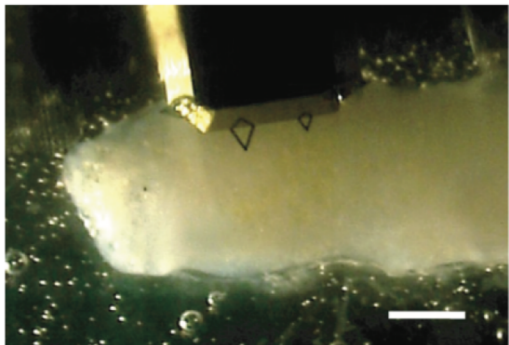
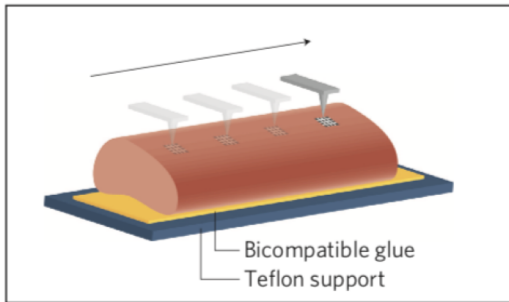
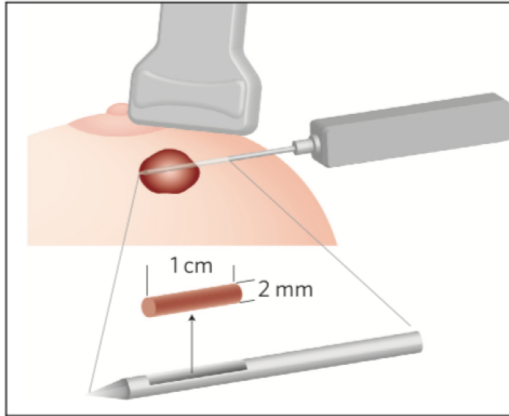
ARTICLES

PUBLISHED ONLINE: 21 OCTOBER 2012 | DOI: 10.1038/NNANO.2012.167

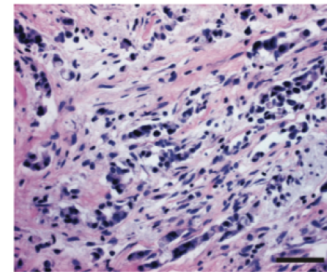
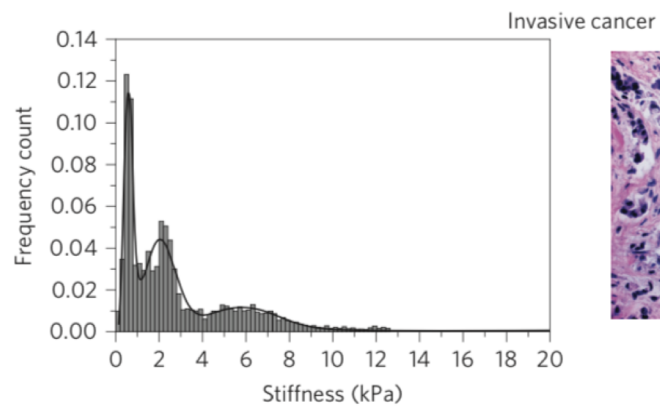
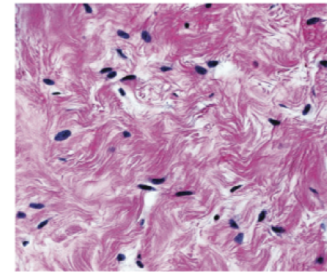
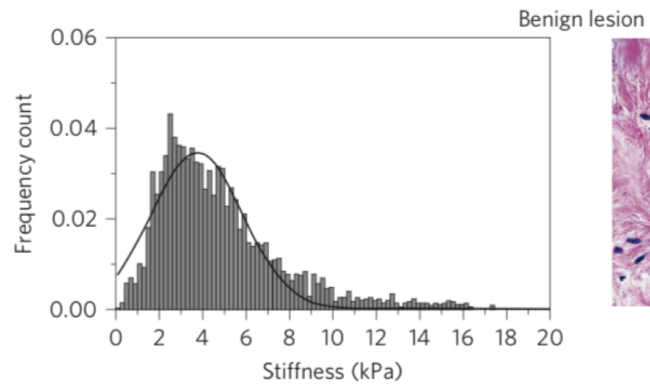
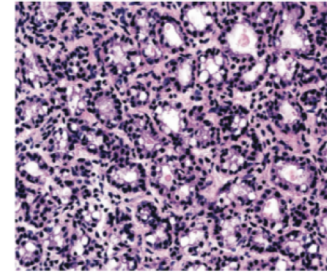
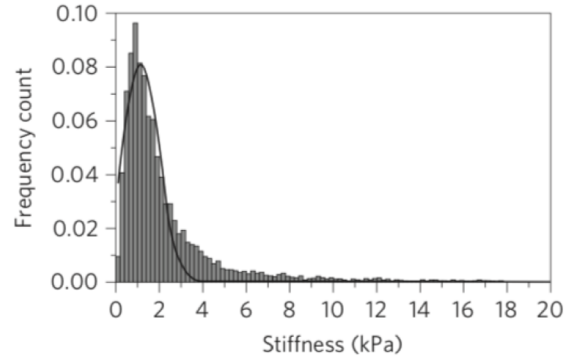
The nanomechanical signature of breast cancer

Marija Plodinec^{1,2}, Marko Loparic^{1,2†}, Christophe A. Monnier^{1†}, Ellen C. Obermann^{3†},
Rosanna Zanetti-Dallenbach^{4†}, Philipp Oertle¹, Janne T. Hyotyla¹, Ueli Aebi², Mohamed Bentires-Alj⁵,
Roderick Y. H. Lim^{1*} and Cora-Ann Schoenenberger²

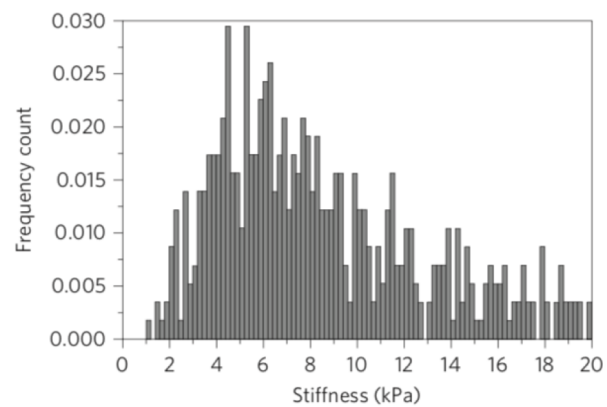
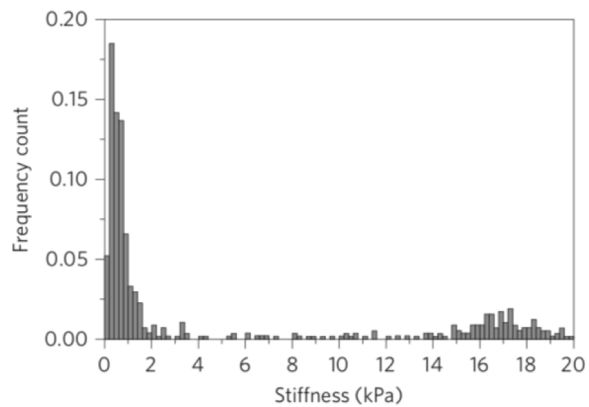
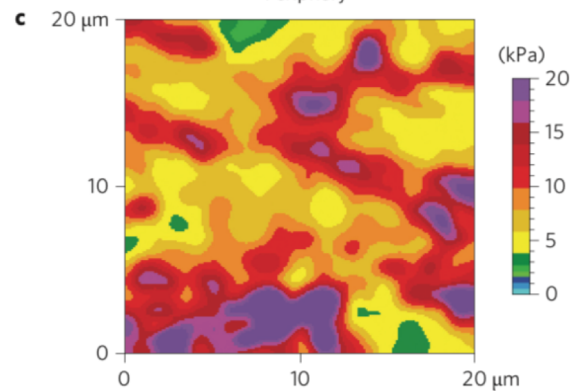
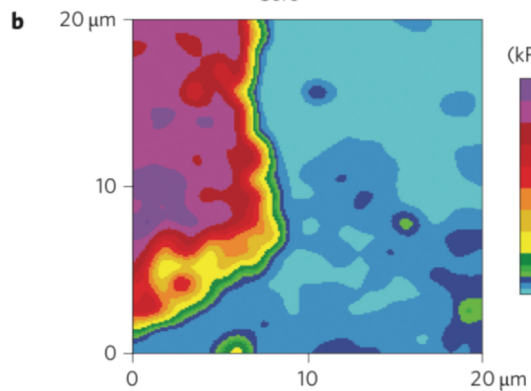
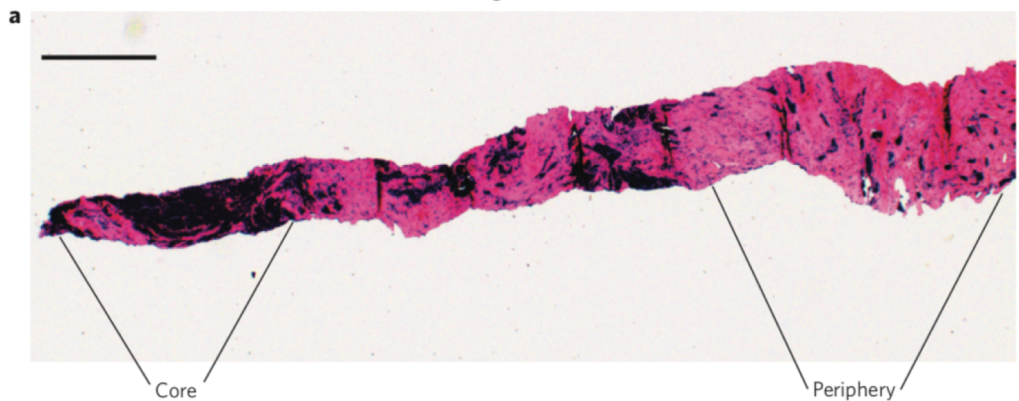
a Testing human breast biopsies by IT-AFM



b Normal tissue



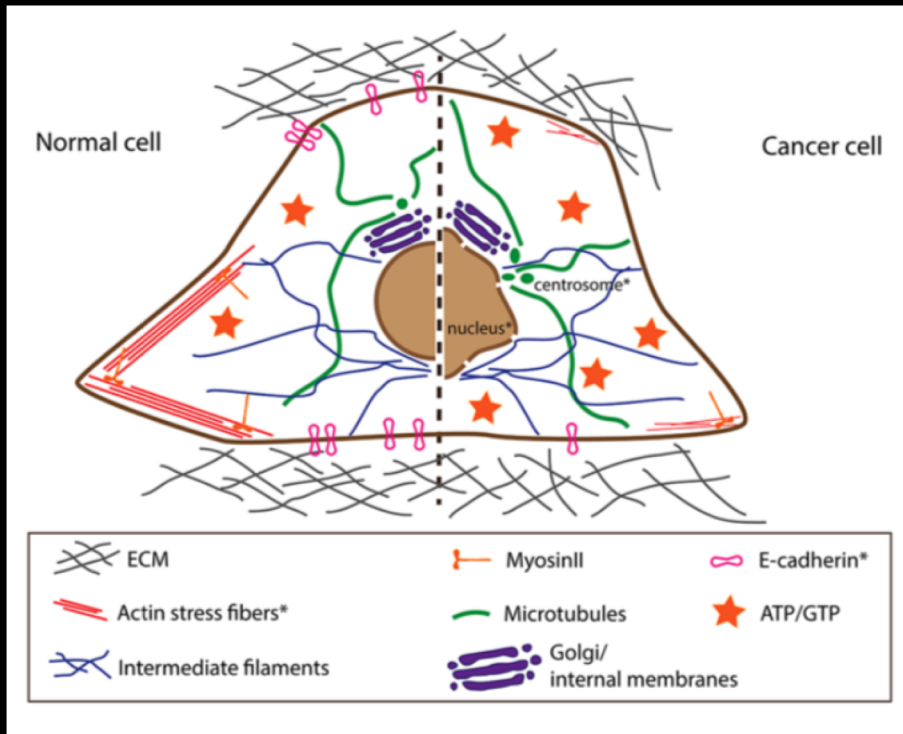
Histological overview



Are cancer cells really softer than normal cells?

Charlotte Alibert*†, Bruno Goud*† and Jean-Baptiste Manneville*†¹

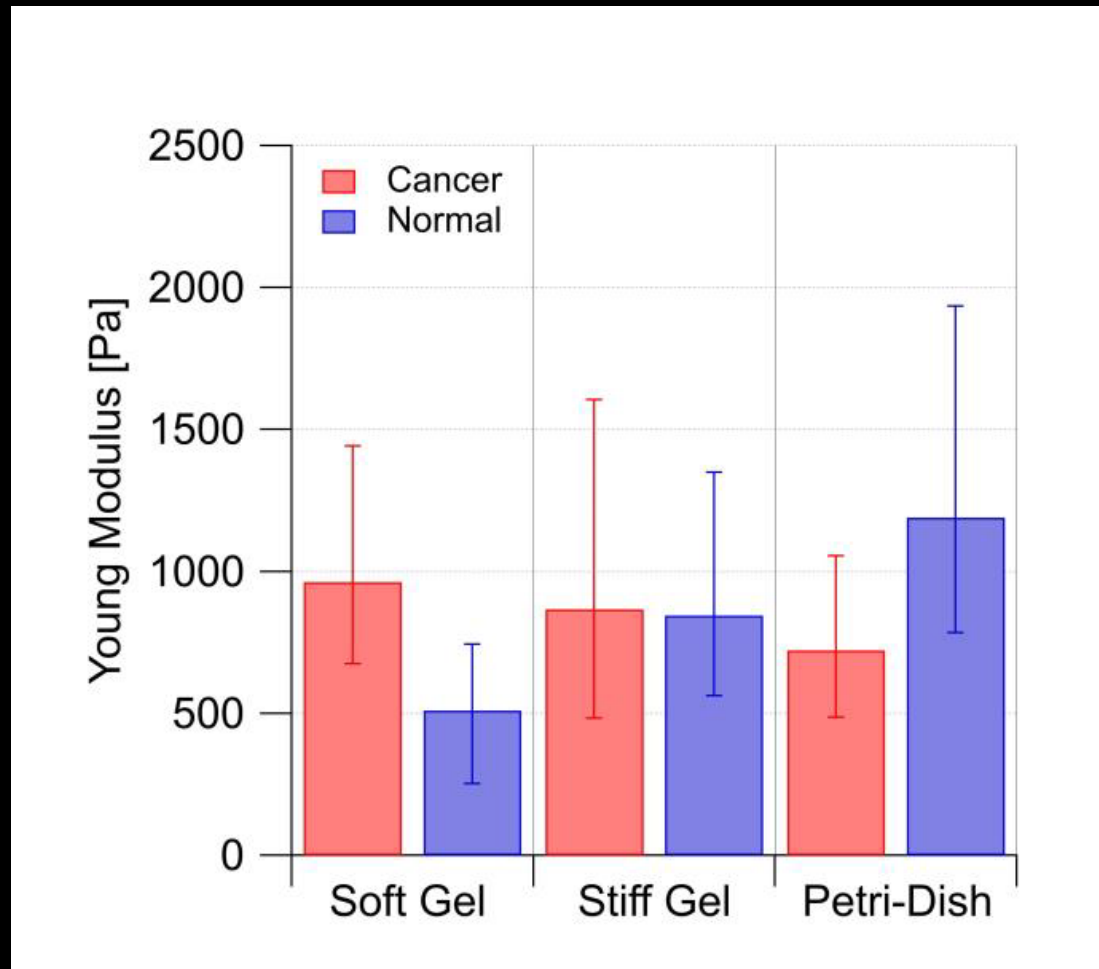
*Institut Curie, PSL Research University, CNRS, UMR 144, Paris, France and †Sorbonne Universités, UPMC University Paris 06, CNRS, UMR 144, Paris, France



Biol. Cell (2017) 109, 167-189

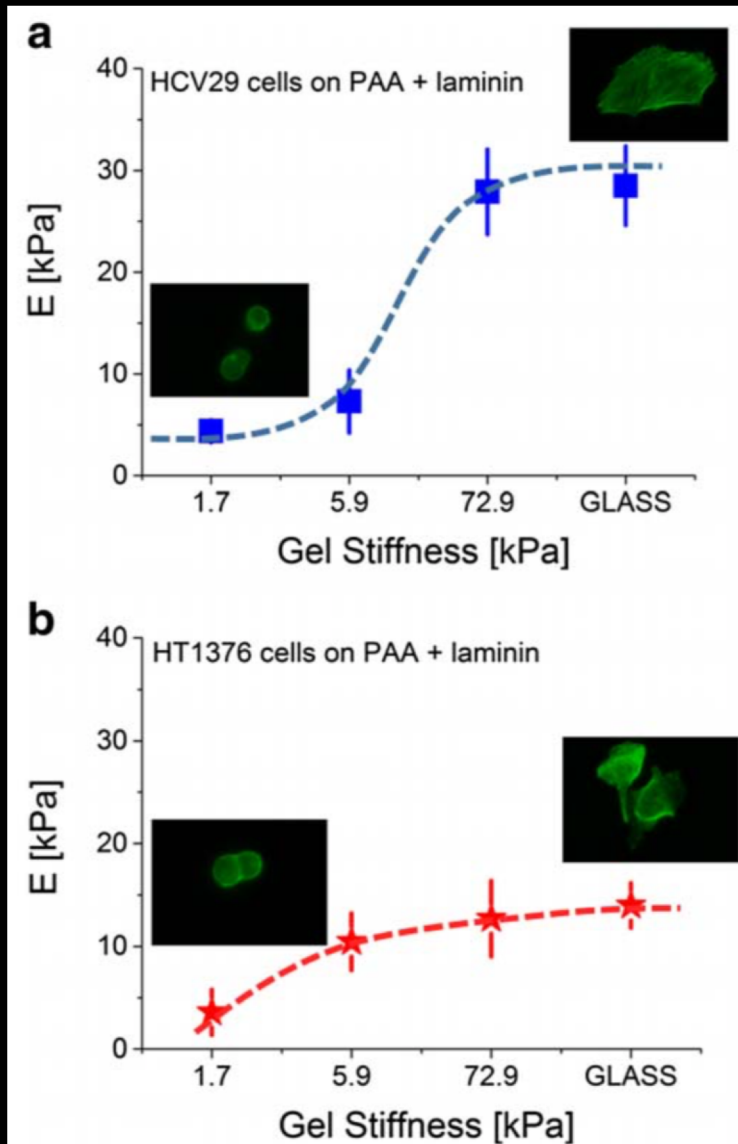
“The mechanical properties of cancer cells could thus be used as novel diagnostic and/or prognostic markers to complement histological examinations and genetic phenotyping of the tumour”

Cells on different stiffness substrates



C. Rianna, M. Radmacher, Eur. Biophys. J. (2016)

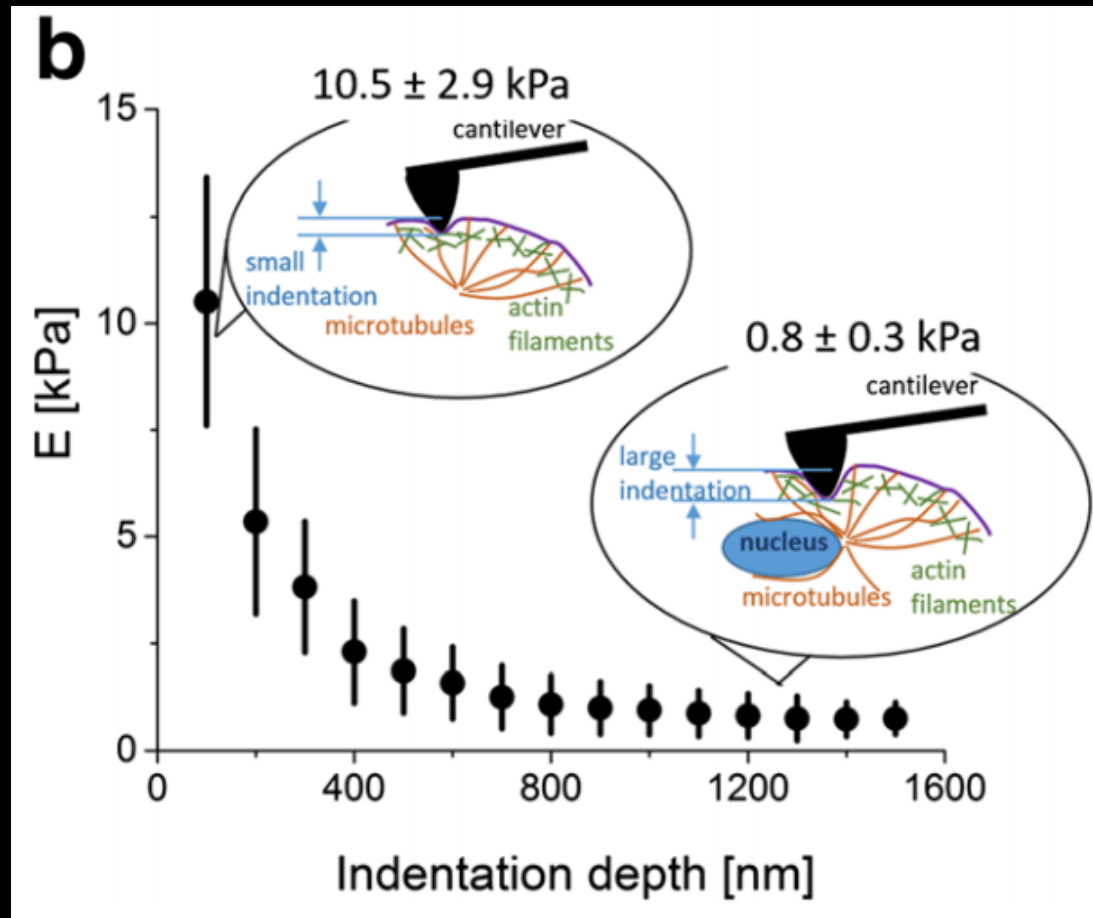
Cells on different stiffness substrates



non-malignant cancer cells HCV29

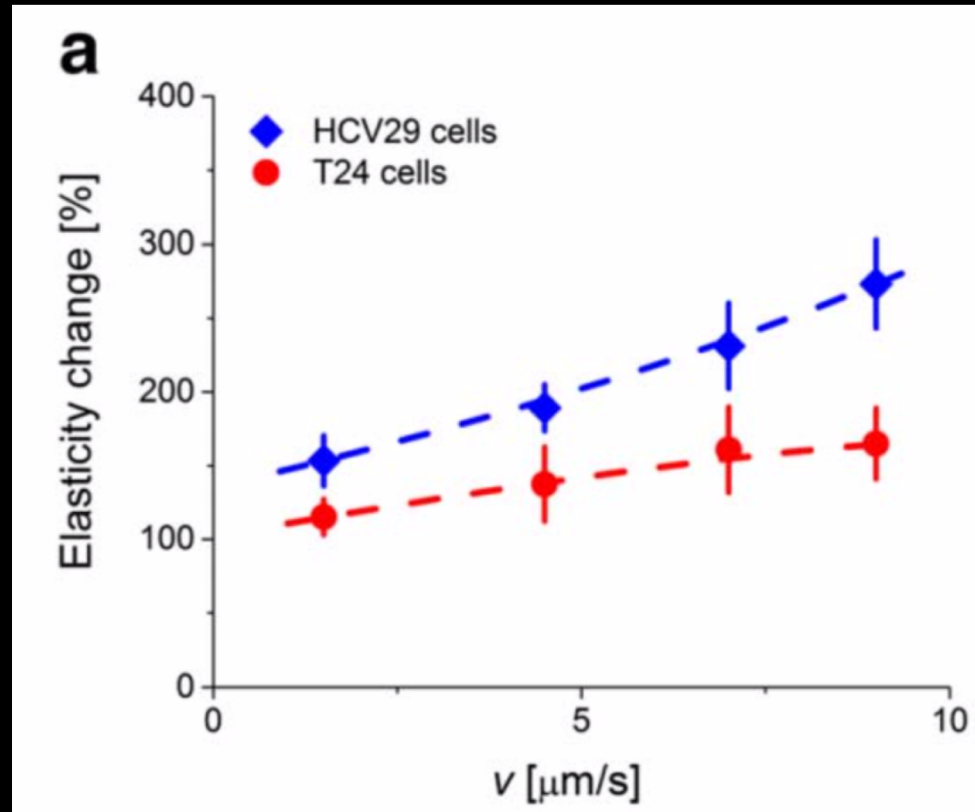
human bladder cancer cell HT1376

Indentation depth



- small indentation depths < 200 nm: mechanical response of the actin network
- larger indentation depths: the overall elasticity of the whole cell

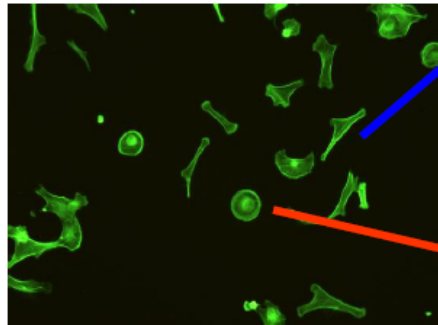
Tip velocity



⇒ Measured Young's modulus depends on approach speed (tip velocity)

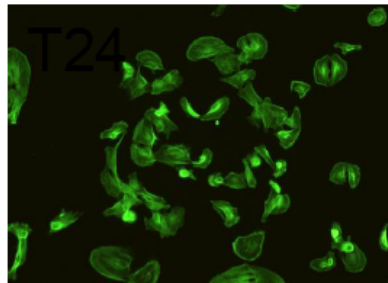
⇒ Cells appear stiffer at higher velocities

Cancer cell recognition

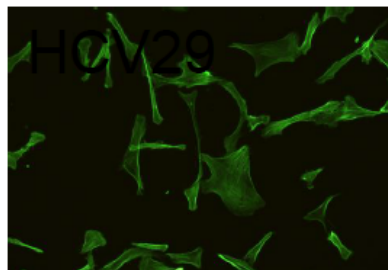


HCV29

T24

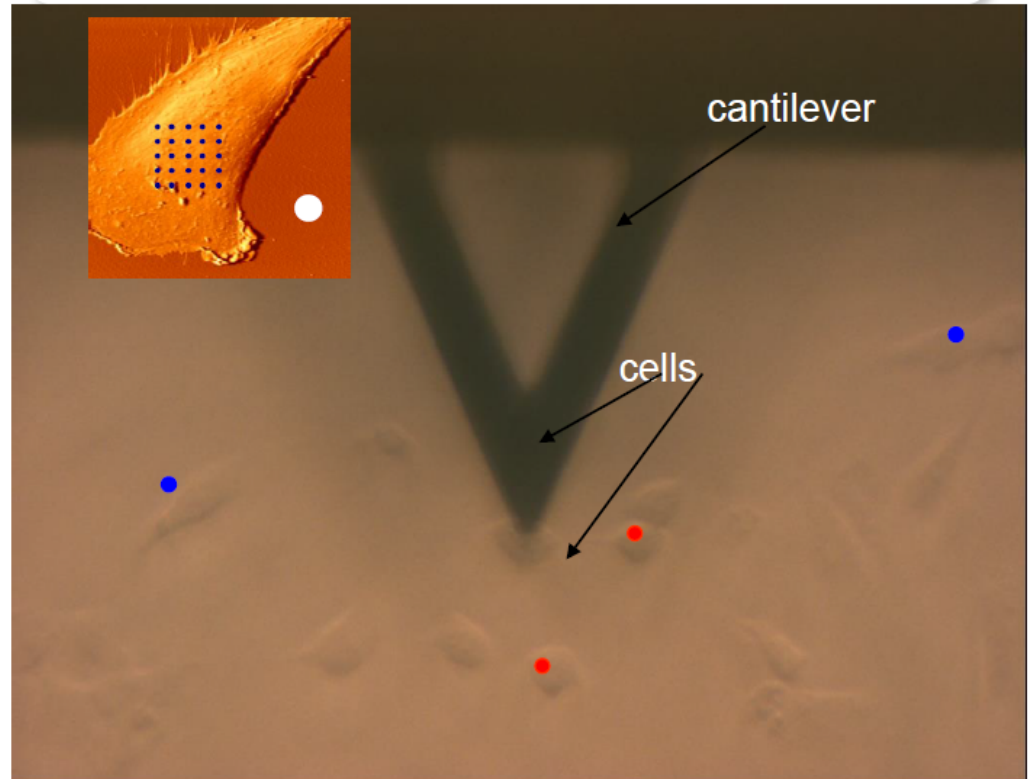


T24



HCV29

Can we recognized mechanically altered cell in the environment of other cells ?



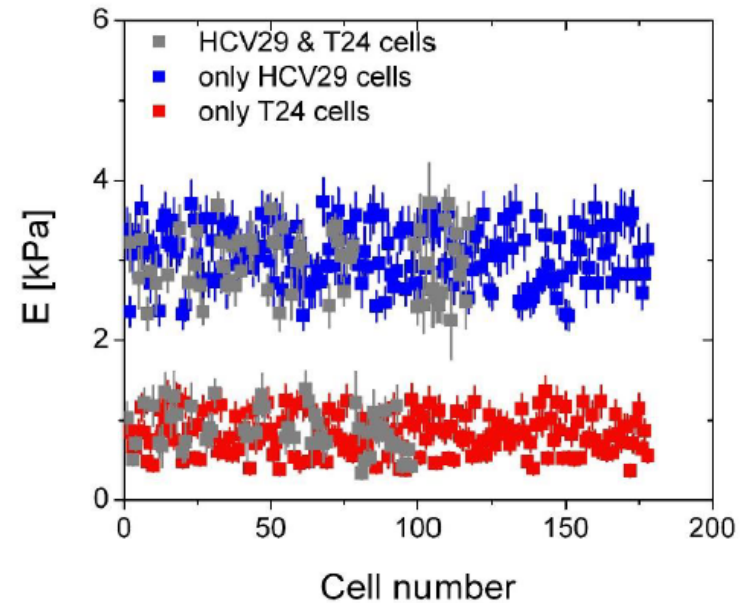
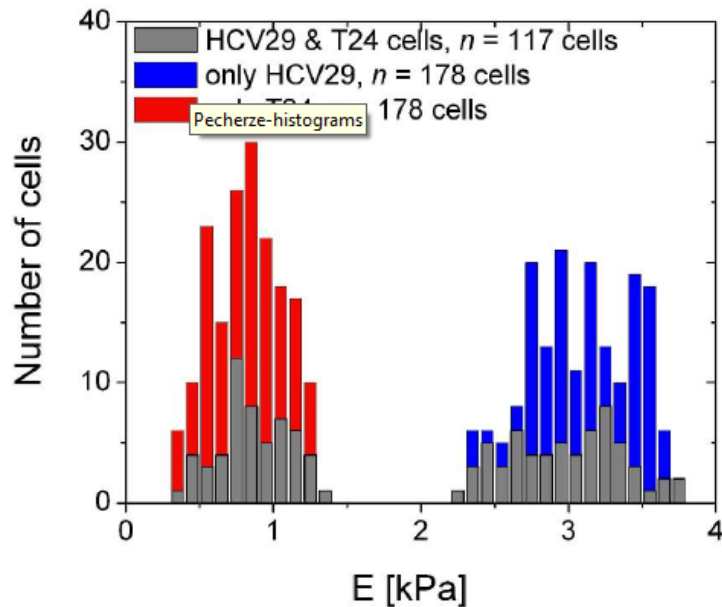
cantilever

cells

initial cell number

44000 (T24) and 67000 (HCV29) per ml; 24h of growth

Cancer cell recognition

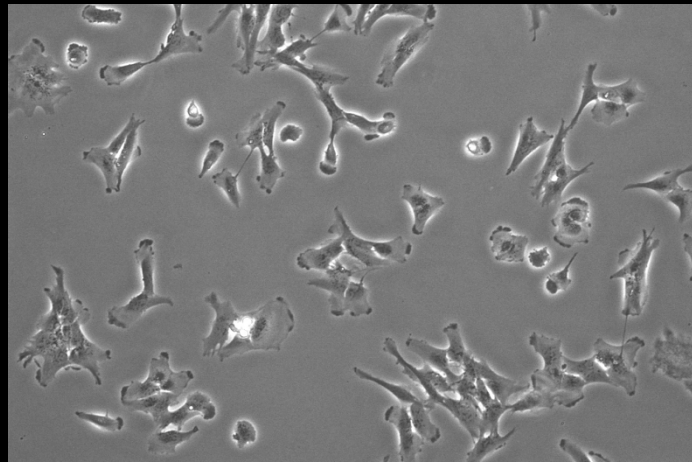


initial cell number 44000 (T24) and 67000 (HCV29) per ml; ratio 1:0.7; 96h

Same results as for separate cell lines

Autophagy and cell mechanics

Cells seeded on glass surfaces adopt different shapes

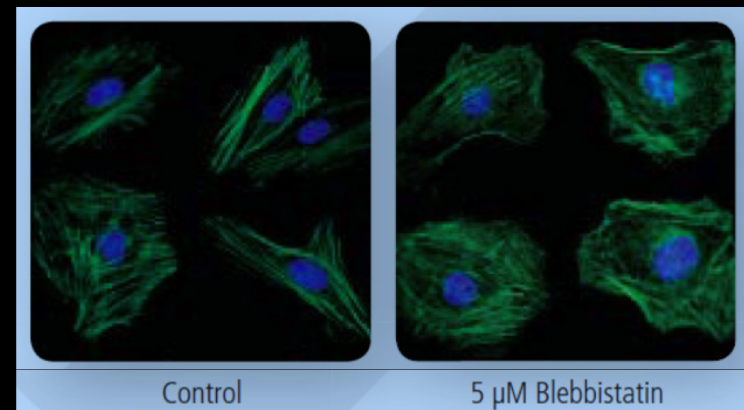
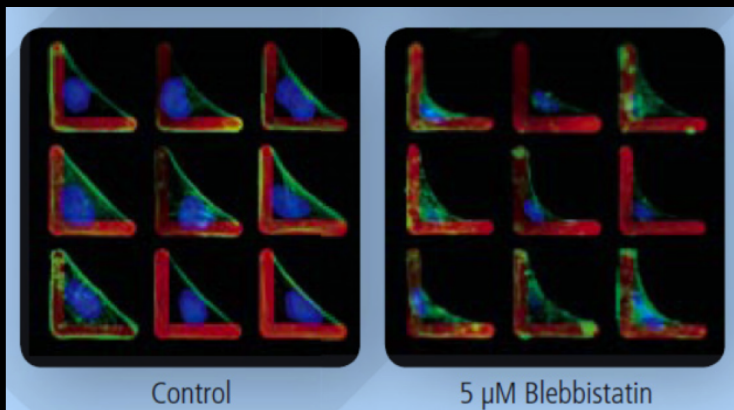


→ not convenient to easily quantify drug effect on cells

→ **Micropatterning**

Autophagy and cell mechanics

By growing cells on adhesive micropatterns, a well defined and confined environment is imposed that drives cells to adopt **regular shapes** and **cytoskeletal organization**.



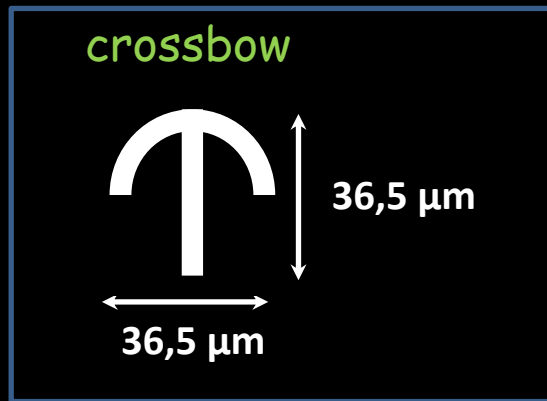
<https://cytoo.com>

→ Defined cell adhesion geometry (to control cellular processes or to mimic spatial constraints that a cell is exposed inside a tissue)

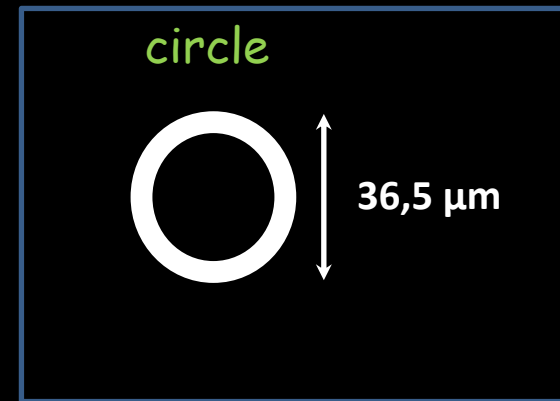
Autophagy and cell mechanics

Patterning

Micropatterns :



→ Strong polarization



→ Non-polarized

simulate the shape of a migrating cell with the rounded edge mimicking a lamellipodium at the front of a migrating cell.

→ cells of controlled and regular shapes

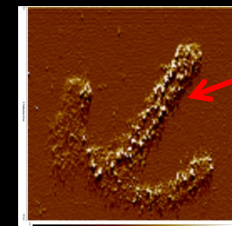
Autophagy and cell mechanics

→ Glass coverslips coated with poly-L-lysine functionalized with poly-ethylen glycol chains (PLL-g-PEG)

→ Coating removed at precise locations with a defined shape (crossbow) by illumination through a photo mask (or PRIMO).

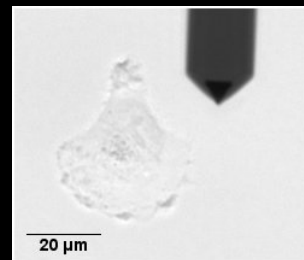


→ The resulting « holes » were then filled with fibronectin

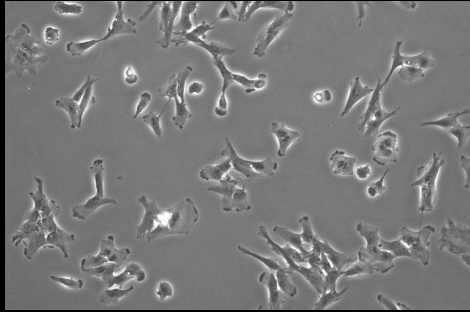


fibronectin

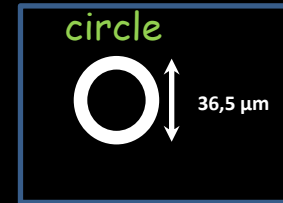
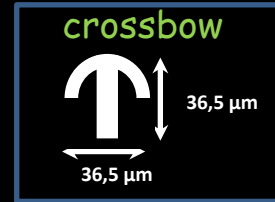
→ RPE1 cells were then seeded onto the micro-patterns



Influence of autophagy on cell mechanics

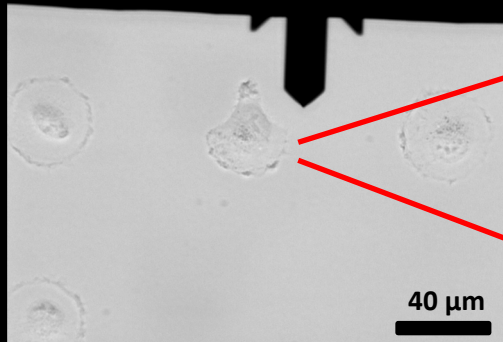


→ Micropatterning

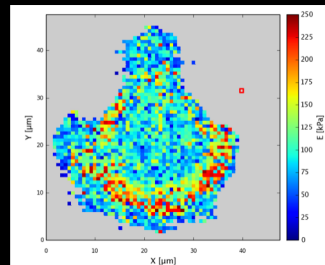


→ cells of controlled and regular shapes

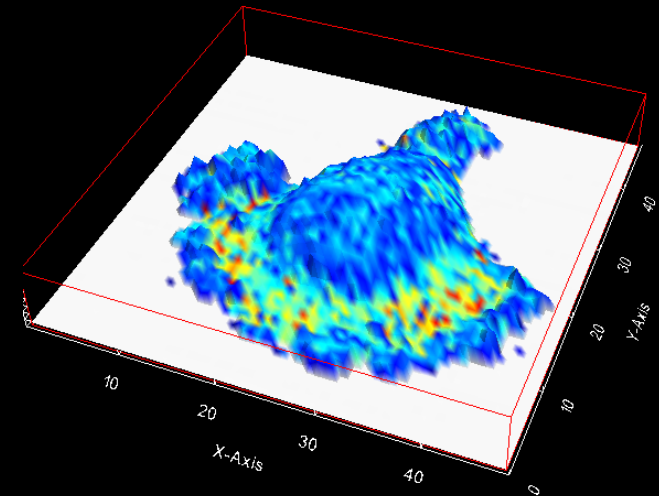
Cell mechanics



E (kPa)
(Sneddon model)



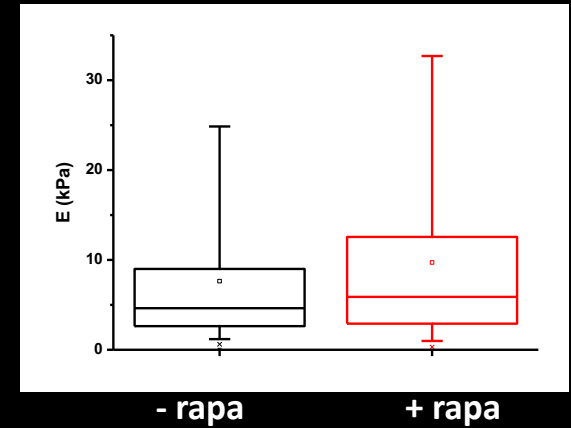
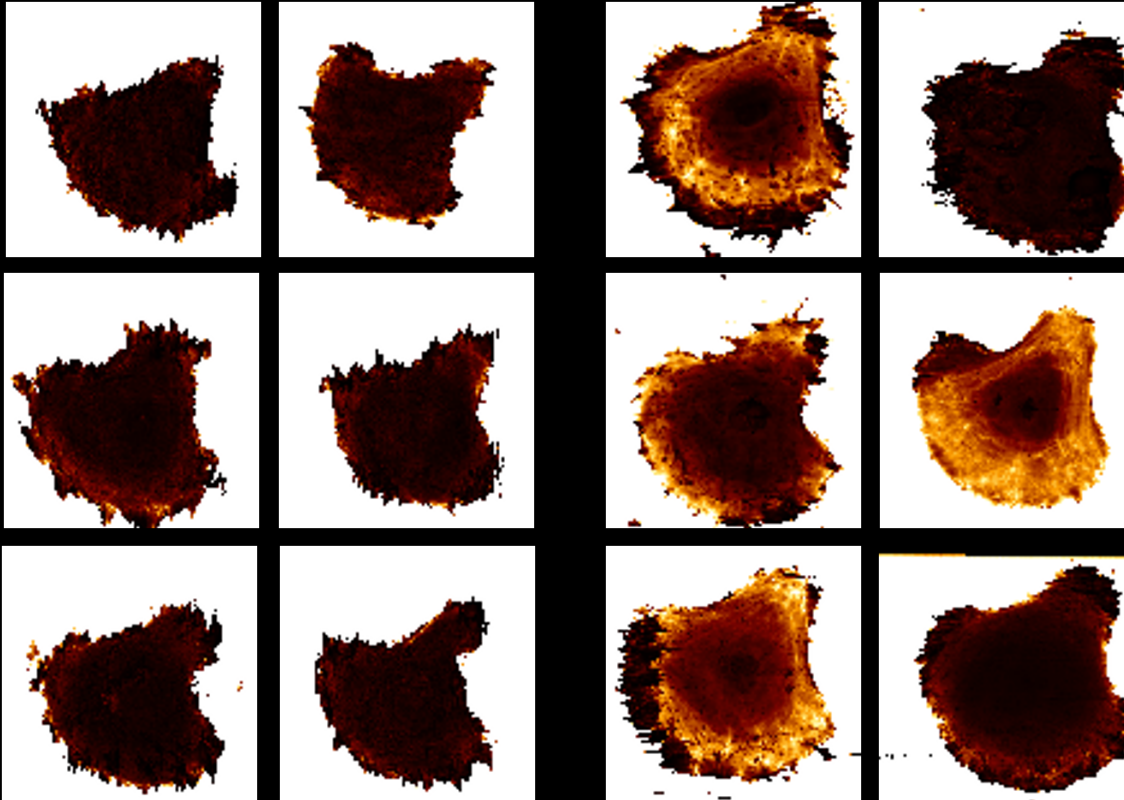
Elasticity map



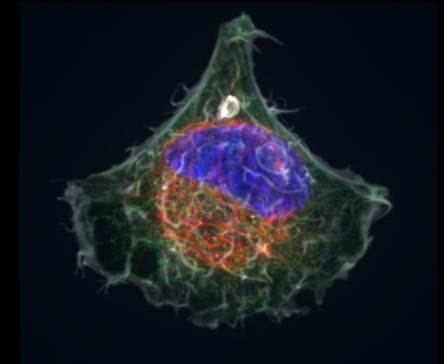
Influence of autophagy on cell mechanics

Without rapamycin

With rapamycin

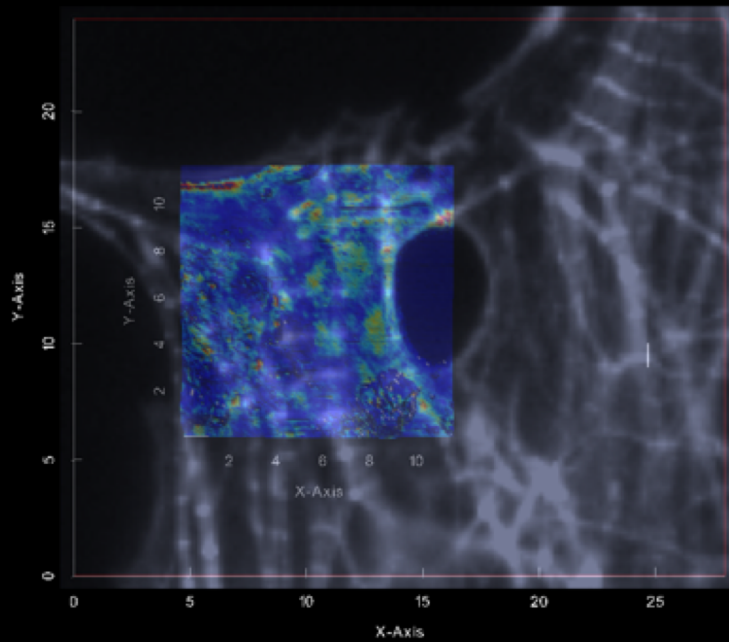
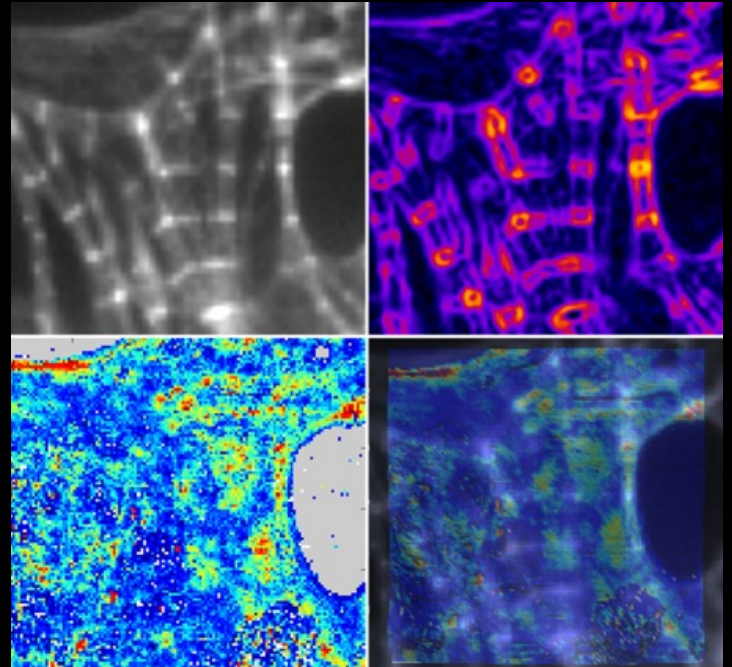
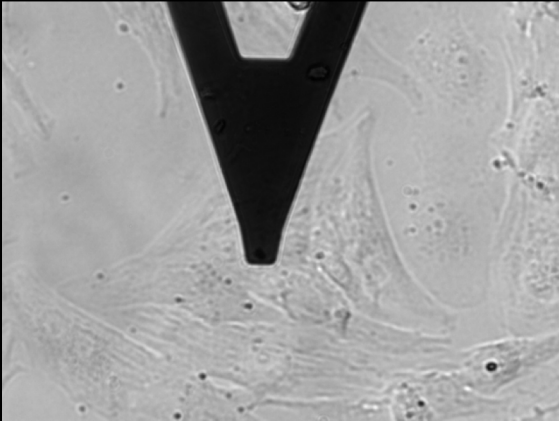


→ Cytoskeleton organization : High resolution imaging (STED)

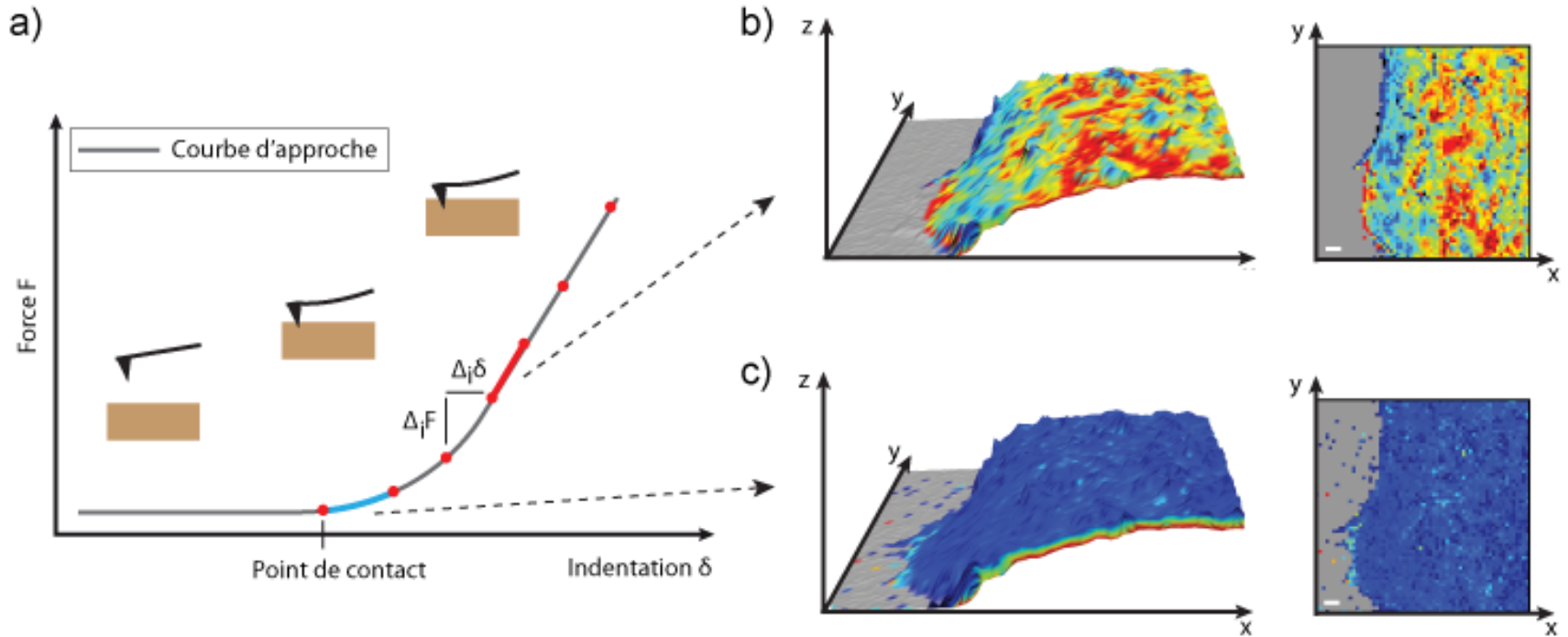


Coupling

Cardiomyocytes



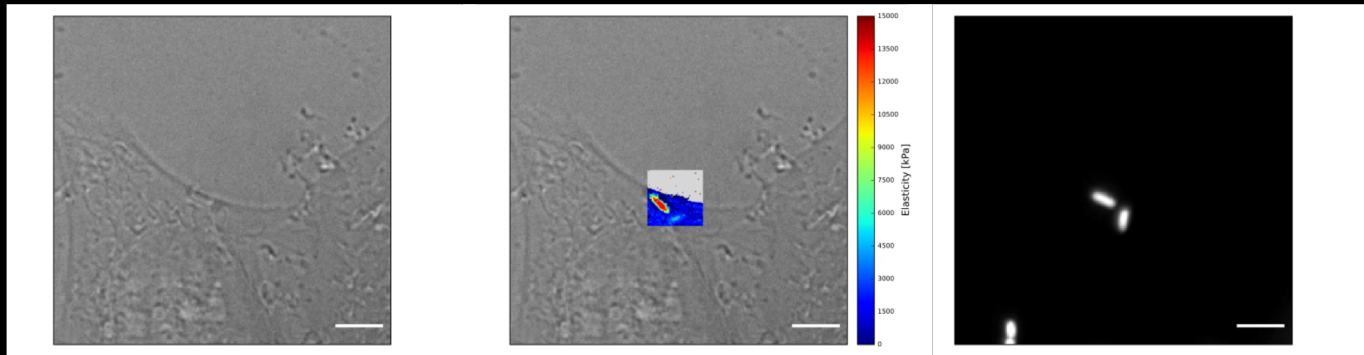
Stiffness tomography



Stiffness tomography

SITE D'ENTREE DE YERSINIA

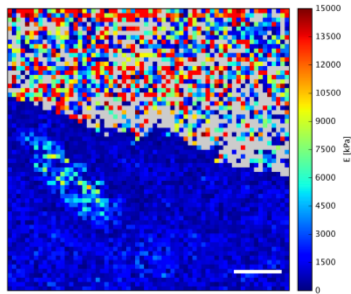
Infection de cellules HeLa par *Y. pseudotuberculosis*



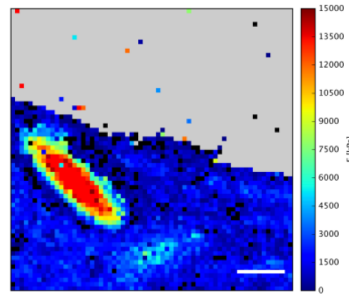
Lumière transmise

Corrélation

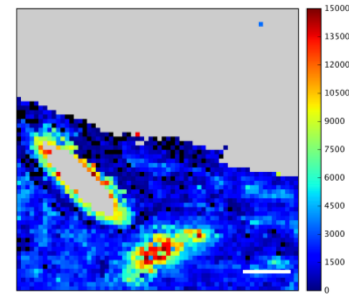
Fluorescence



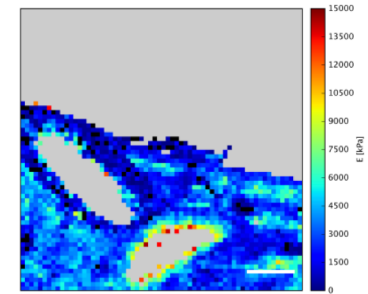
Élasticité 0-10 nm



Élasticité 30-40 nm



Élasticité 70-80 nm



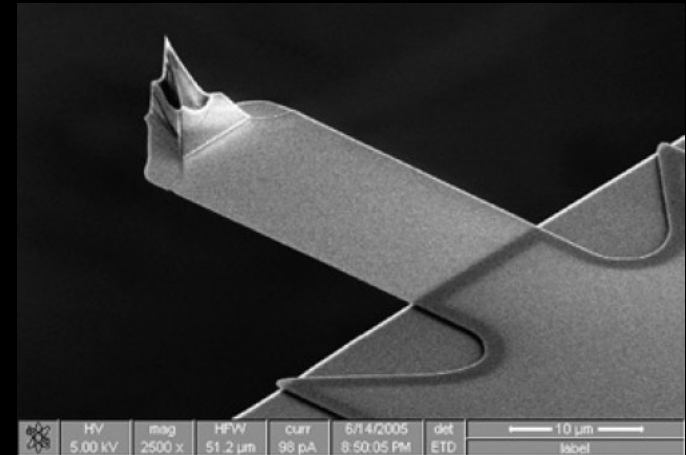
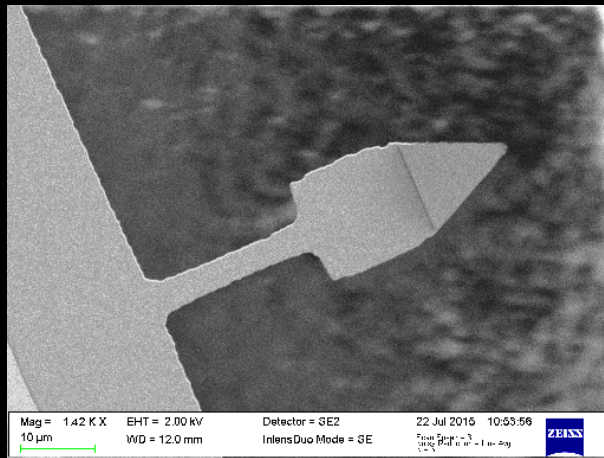
Élasticité 130-140 nm

- 1) How can we measure cell mechanics by AFM ?
- 2) Why (cell mechanics in diseases) ?
- 3) **Perspectives**

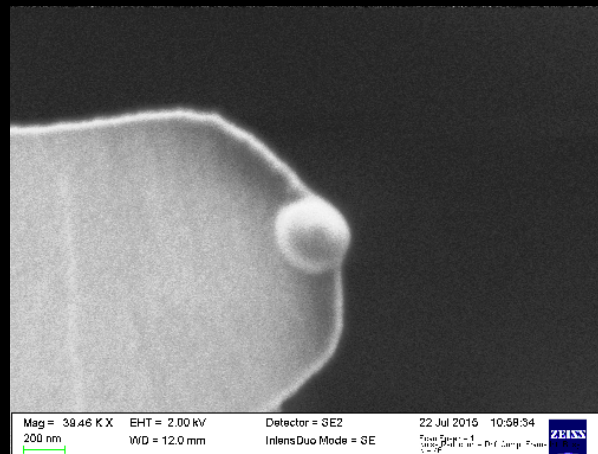
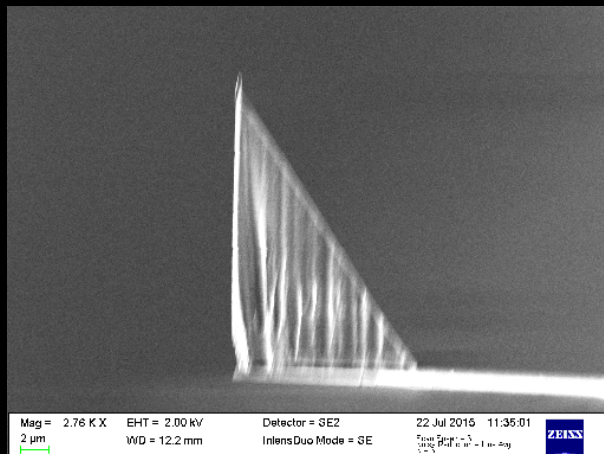
Perspectives : resolution

Recent AFM developments :

- new probes
- new modes (FV → QI, PFT)



BioLever Mini (AC40 – Bruker)
110 kHz Air, 25 kHz Fluid, 0.1 N/m

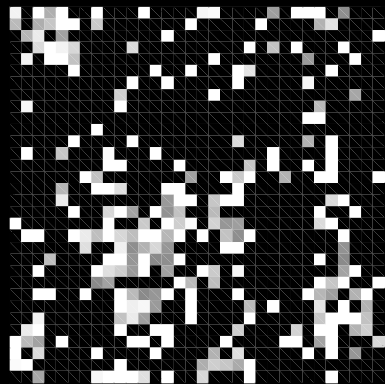
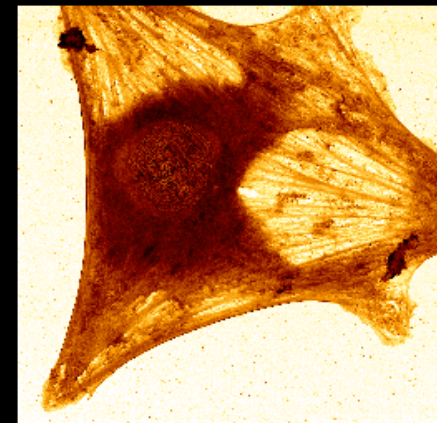
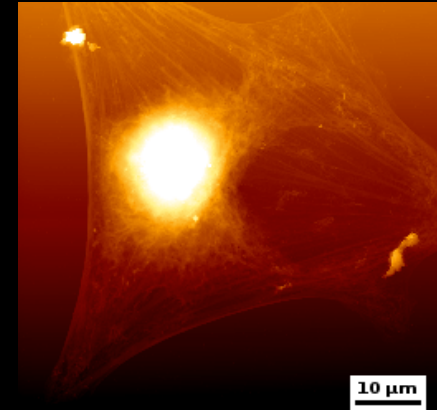


PeakForce QNM-LC (Bruker)

Perspectives : resolution

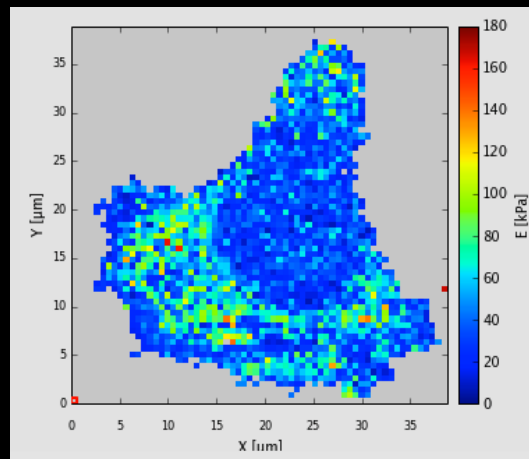
Recent AFM developments :

- new probes
- new modes (FV \rightarrow QI, PFT)



FV 32*32

Acquisition : 30 à 45min
Treatment : \approx 3-4 heures



QI 64*64

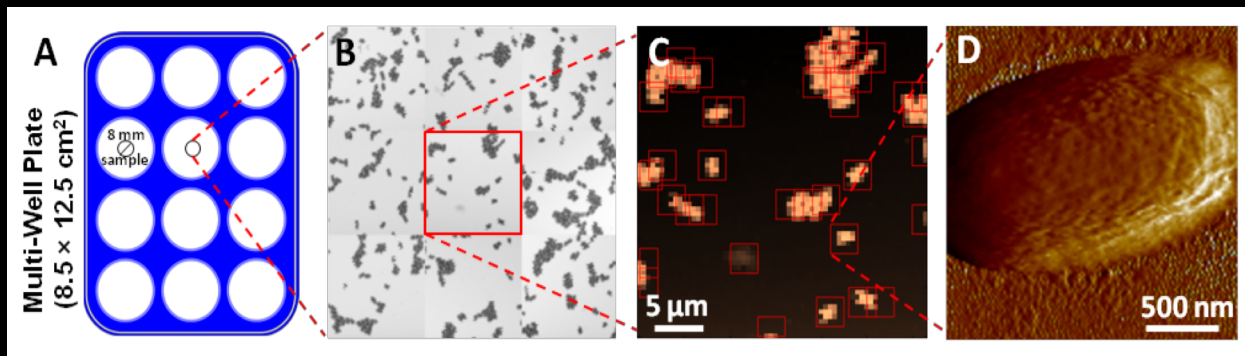
Acquisition : \approx 5 min
Treatment : \approx qq minutes

QI 256*256

Acquisition : \approx 10 min
Treatment : \approx qq minutes

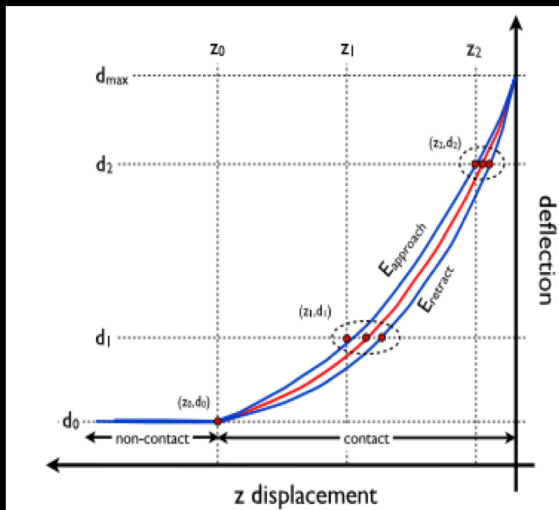
Perspectives

→ automation (middle - high-throughput)

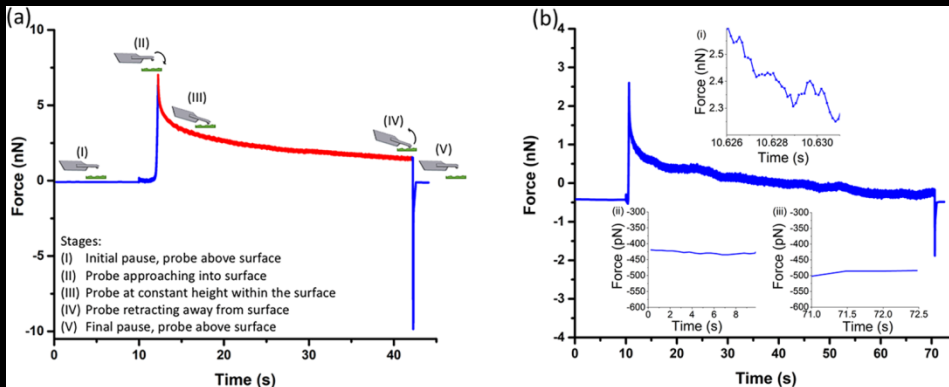


Perspectives

→ viscosity (viscoelastic properties)

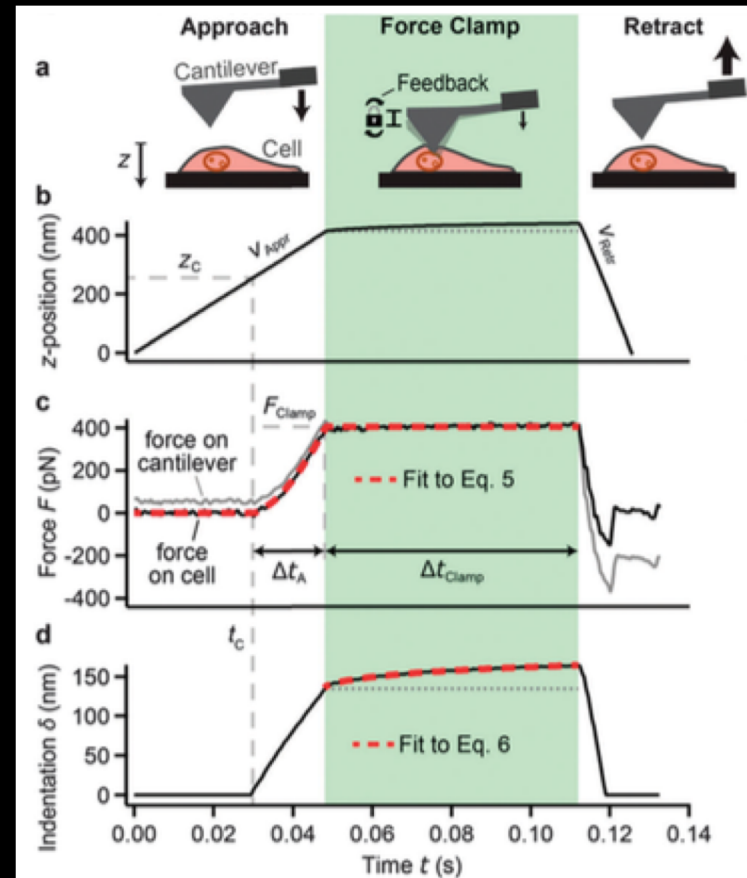


Rebello *et al.*, Nanotechnology (2013)

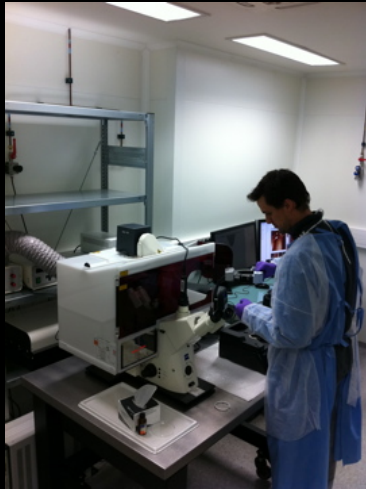


Chim *et al.*, Sci. Rep (2018)

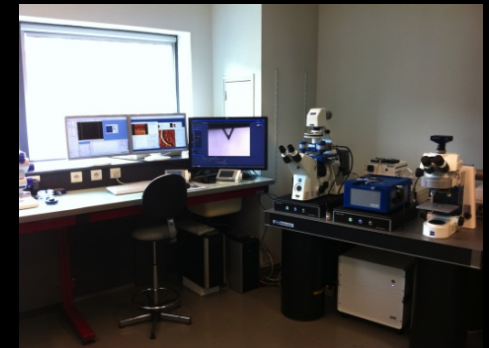
Force Clamp Force Mapping



Hecht *et al.*, Soft Matter (2015)



<http://www.cmpi.cnrs.fr/>



vincent.dupres@ibl.cnrs.fr

Mardi 19 mars 2019

Atelier 1 : Mécano biologie
(S. Janel)

