

Pourquoi (j'aime bien) Kokkos ? Modern C++, portabilité de performance, ...

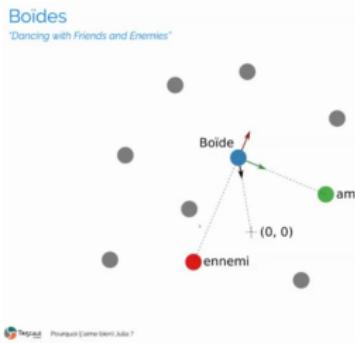
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Café CALCUL - 22 octobre 2021

Plan

- 8 avril 2021 : Café Calcul - Pourquoi Julia ? (F. Févotte)
le problème des deux langages (script polyvalent + bas niveau performant)
⇒ **Julia**
- le problème du modèle de programmation (polyvalent, multi architecture)
⇒ **portabilité de performance**



nanoApp : (naively) revisiting boids flight with Kokkos,
<https://github.com/pkestene/kboids>

(Pre-)Exascale machines - architecture diversity !

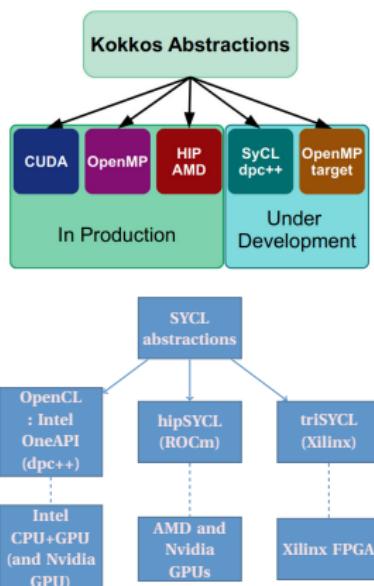
- **US:** Summit , Sierra ⇒ mostly OpenPower (IBM P9 + Nvidia V100), GPU-based architecture, #2 and #3 @top500; exascale machines announced
 - Aurora (Argonne NL, 2022): Intel Xe GPU
 - Frontier (Oak Ridge NL, 2021 ?): AMD EPYC + Radeon Instinct GPU
- **China:**
 - Phytium FT2000/64 ARM chips + Matrix2000 GPDSP accelerators ⇒ #6 @top500, Tianhe-2A, 61 PFlops
 - 260-core Shenwei, **homegrow technology** hardware + software (C++/fortran compiler + OpenACC) ⇒ #4 @top500 , Sunway TaihuLight, 105 PFlops
 - Dhyana, AMD-licensed x86 multicore (300 M\$), identical to AMD EPYC
- **Japan:** Fugaku(Fujitsu, ARM, RIKEN) A64FX ARM (**home grown**, started in 2014, **#1 @top500 (Nov. 2020)**, 900 M\$), GPU, etc ...
- **Europe** : new organization EuroHPC (2018), EC H2020 budget (~ 500 M€ per year)
home grown (EPI) ARM and RISC-V architecture, early stage

Motivations for performance portability

- What is performance portability ?
 - **(Re)write your code once, (try to) run *efficiently everywhere***
 - By everywhere, we mean : Multicore Intel/ARM and Nvidia/AMD GPUs
 - **High-level approach:** as much as possible (if possible) hide hardware details to the (physicist / applied math) software developer
 - <https://performanceportability.org>
 - 1st annual DOE Performance Portability Meeting (2016)
- Is that **possible** ?
 - How ?
 - Which programming model ?
 - Which language ?
 - Which compiler ? ⇒ large combinatorics
- for the rest of this talk, i'll focus on the kokkos/C++ library

Parallel programming models landscape

- **Low-level native language:** OpenCL, CUDA, HIP
- **Directive approach (code annotations)** for multicore/GPU, ...:
 - OpenMP 5.1 (Clang, PGI, GNU, ...), OmpSs-2
 - OpenACC 2.7 (PGI, GNU, ...) ⇒ Fortran codes.
- **Other high-level library-based approaches:**
 - Kokkos, RAJA, Alpaka, HPX, GridTools, ArrayFire...
 - **SYCL** (Khronos Group *standard*), C++ high-level layer on top of OpenCL. Intel OneAPI/DPCPP (Intel CPU/GPU/FPGA, Nvidia GPUs), CodePlay, AMD and Nvidia GPUs, Keryell/Xilinx
 - **C++17 built-in parallelism for multicore and GPUs**, e.g.:
 - Nvidia's hpc-sdk (May 2020)
 - Intel OneAPI/TBB



additionnal features:

memory management,
data containers, ...

Kokkos (2010), before C++-11 and lambdas

- Before 2010, starts as a refactoring of Trilinos (10.4), **abstract concept of Node** (generic for SerialNode, TBBNode or CUDANode)
conf paper: A light-weight API for portable Multicore Programming

```
// data-work struct
template <class Node>
class ApxyOp {
    Node::buffer x,y;
    double alpha,beta;
    void execute(int i);
};

template <>
void SomeNode::parallel_for<ApxyOp>(int begin, int end, ApxyOp wd) {
    // node specific implementation
    // if SomeNode == TBB, then call TBB API
    // if SomeNode == CUDA, then call Cuda thrust::for_each
    // ...
}
```

Kokkos: a programming model for perf. portability

- Kokkos is a **C++ library** for **node-level parallelism** (i.e. **shared memory**) providing abstractions for **hardware-aware**:
 - **parallel algorithmic patterns**
 - **data containers**
- <https://kokkos.org/>
- Implementation relies heavily on **C++ meta-programing** to derive native low-level code (OpenMP, CUDA, HIP, SYCL...) and adapt data structure memory layout at compile-time
- Developped at **Sandia NL** (core, CUDA, OpenMP), **ORNL** (HIP, SYCL), ...

Goal: write one implementation which:

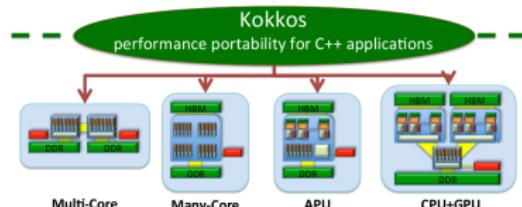
- compiles and **run on multiple archs**,
- obtains **performant memory access pattern** across archs,
- can leverage **arch-specific features** where possible.

Kokkos: a programming model for perf. portability

- Open source, <https://github.com/kokkos/kokkos>
- Primarily developed as a base building layer for **generic high-performance parallel linear algebra** in [Trilinos](#)
- Used in, e.g.:
 - [LAMMPS](#) (molecular dynamics code),
 - [NALU CFD](#) (low-Mach wind flow),
 - [SPARTA/DSMC](#) (rarefied gas flow), [SPARC](#) (CFD, RANS, LES, hypersonic flow)
 - [Albany](#) (fluid/solid,...)
 - [Uintah](#) (structured AMR, combustion, radiation)

Strong involvement in
ISO/C++ 2020 Standard

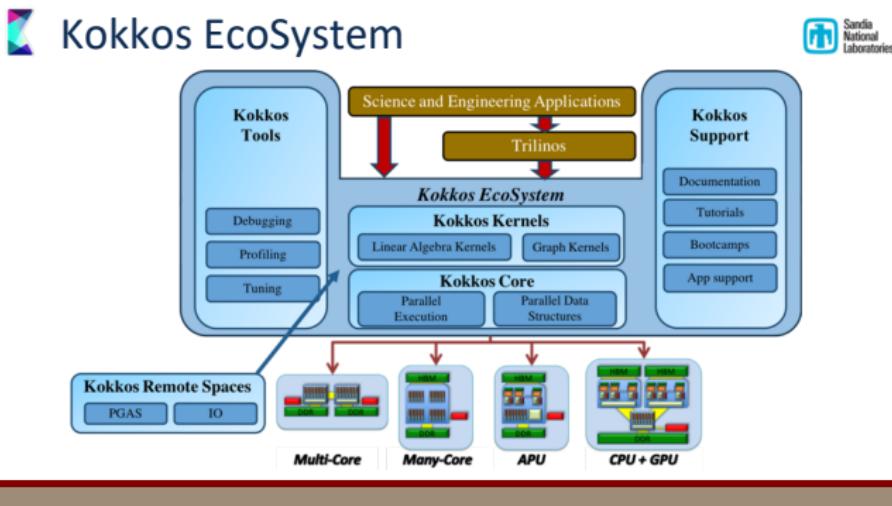
Make Kokkos a sliding
window of future c++
features



see mdspan proposal <https://github.com/kokkos/mdspan>

<https://arxiv.org/abs/2010.06474>

Kokkos: a programming model for perf. portability



- Kokkos-kernels (many dense/sparse BLAS problems, ...), simd-math, Cabana (for particle-based codes)
- Fortran compatibility layer (REX code XGC-Cabana, Plasma physics, Gyrokinetics, particle-in-cell)
- pykokkos-base (pybind11-based API mapping + memory, numpy/cupy interoperability), pykokkos (decorator + python to C++ translation)
- Task-DAG parallelism (CPU / GPU)

source: C. Trott, DOE Performance Portability Meeting, April 2019

Kokkos - Documentation

- Kokkos video lectures + slides :
<https://github.com/kokkos/kokkos-tutorials/wiki/Kokkos-Lecture-Series>
- Kokkos tutorial : <https://github.com/kokkos/kokkos-tutorials>
- Kokkos source code itself, reading unit tests code is also very helpful

Illustrating portability with Kokkos

```
for(int j=0; j<ny; ++j)
    for(int i=0; i<nx; ++i)
        data[i+nx*j] += 42;
```

Question: Assuming 2d data with **left layout**, but only 1 loop to parallelize, which one would you prefer to parallelize (inner or outer) ?

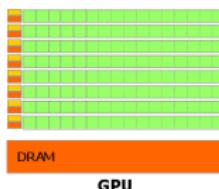
left-layout = row-major

$n_x(n_y - 1)$	$n_x(n_y - 1) + 1$...	$n_x n_y - 1$
:	:	..	:
$2n_x$	$2n_x + 1$...	$3n_x - 1$
n_x	$n_x + 1$...	$2n_x - 1$
0	1	...	$n_x - 1$

Answer:
Optimize memory access pattern !

- maximize cache usage + SIMD for CPU
- maximize memory coalescence on GPU

Different hardware ⇒
Different parallelization strategies

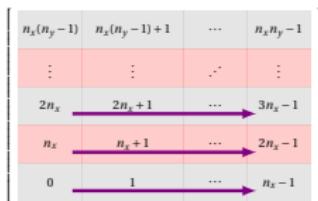


Illustrating portability with Kokkos

Question: Assuming 2d data, **left layout**, which loop would you prefer to parallelize (inner or outer) ?

OpenMP // outer loop

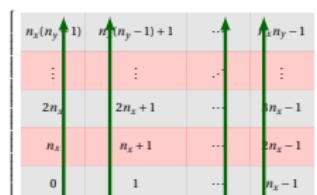
```
#pragma omp parallel
{
    #pragma omp for
    for(int j=0; j<ny; ++j)
        #pragma omp simd ivdep
        for(int i=0; i<nx; ++i)
            data[i+nx*j] += 42;
}
```



CUDA // inner loop

```
--global__ void compute(int *data)
{
    // adjacent memory cells
    // computed by adjacent threads
    int i = threadIdx.x + blockIdx.x*blockDim.x;

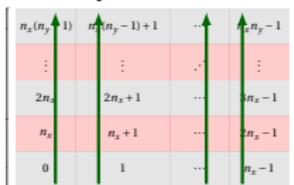
    for(int j=0; j<ny; ++j)
        data[i+nx*j] += 42;
}
```



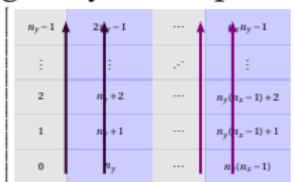
Illustrating portability with Kokkos

Let's **choose** memory layout at compile-time
Make it hardware aware.

left layout / CUDA



right layout / OpenMP



Kokkos single parallel version (CUDA+OpenMP)

Kokkos/CUDA defaults to **left-layout**

Kokkos/OpenMP defaults to **right-layout**

```
Kokkos::parallel_for(nx,  
                      KOKKOS_LAMBDA(int i) {  
                          for (int j=0; j<ny; ++j)  
                              data(i,j) += 42;  
                      }  
                  );
```

Kokkos Concepts (1) - the abstract machine model

- Kokkos defines an abstract machine model for future large shared-memory nodes made of
 - **latency-oriented cores** (multicore CPU)
 - **throughput-oriented cores** (GPU, ...)

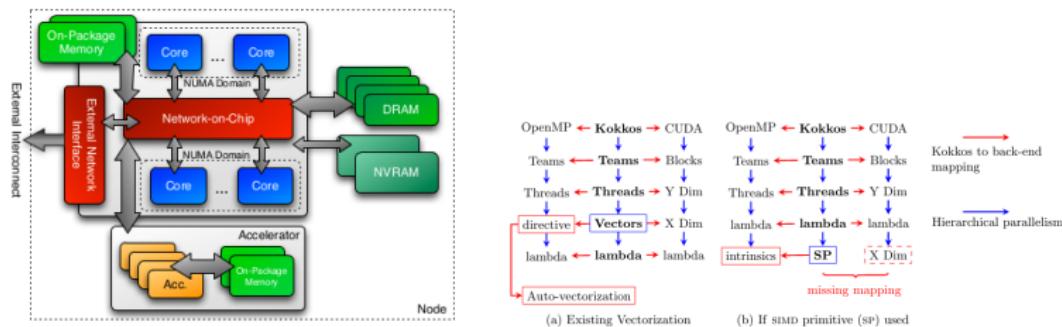


Figure: (left) Conceptual model of a current/future **HPC node**. (Kokkos User's Guide).
 (right) Abstractions mapping.

reference : A portable SIMD primitive in Kokkos for heterogeneous architectures

Kokkos Concepts (2) - What is a device ?

- Kokkos defines several **c++ class** for representing a **device** in **core/src**, e.g.
 - Kokkos::Cuda, Kokkos::HIP, Kokkos::SYCL, Kokkos::OpenMPTarget
 - Kokkos::OpenMP, Kokkos::Threads, Kokkos::Serial
 - **device = execution space + memory space**
- Each *Kokkos device* pre-defines some types
- Example **Kokkos exec space** (not required for a user, only Kokkos developper), e.g.

```
class Cuda {
public:
    // Tag this class as a kokkos execution space
    using execution_space = Cuda;

    #if defined( KOKKOS_USE_CUDA_UVM )
    // This execution space's preferred memory space.
    using memory_space = CudaUVMSpace;
    #else
    // This execution space's preferred memory space.
    using memory_space = CudaSpace;
    #endif

    // This execution space preferred device_type
    using device_type = Kokkos::Device<execution_space,memory_space>;

    // The size_type best suited for this execution space.
    using size_type = memory_space::size_type;

    // This execution space's preferred array layout.
    using array_layout = LayoutLeft;
    ...
} // end class Cuda
```

Kokkos Concepts (3) - execution space, memory space

- **Execution space:** Where should a parallel construct (`parallel_for`, `parallel_reduce`, ...) be executed
 - Special case: `class HostSpace`, special device (always defined) where execution space is either (Serial, Pthread or OpenMP).
 - Each execution space is equipped with a fence: `Kokkos::Cuda::fence()`
- **Memory space:** Where / how data are allocated in memory (HostSpace, CudaSpace, CudaUVMSpace, CudaHostPinnedSpace, HBWSpace, ...)
- **Memory layout** (we will come back later on that)
- Other concepts:
 - Execution policy: used to modify a parallel thread dispatch
- **Multiple execution / memory space** can be used in a single application
See for example in Kokkos sources
`example/tutorial/Advanced_View/07_Overlapping_DeepCopy`
Cuda stream can be used Kokkos; they must be created before `Kokkos::Cuda` exec space

How to Build kokkos (1)



Very large combinatorics of compile options / compiler / target architecture !

- Kokkos is (used to be) mostly header-only; examples can be build using a **standalone Makefile** (provided Kokkos is cloned in your home directory) or **cmake**.

1. Build with standalone Makefile, play with examples:

- 1. `mkdir $HOME/Kokkos; cd $HOME/Kokkos`
some kokkos tutorial examples have a Makefile configured for using that precise location.
 - 2. `git clone https://github.com/kokkos/kokkos`
 - 3. `cd kokkos; git checkout develop`
 - 4. `cd example/tutorial/01_hello_world`

How to Build kokkos (2)

2. Build/install with cmake:

- Note on using vs integrating Kokkos in your own application :
Don't try to add Kokkos source as a git submodule to your project (unless for quick demo ;) ⇒ deprecated

3. Build/install Kokkos with spack:

- ⇒ Kokkos by design has **many different configurations possible** (hardware adaptability, heavily relies on C++ metaprogramming - compile timing)
- For each different configuration, you will have a *modulefile* to configure the environment
- see [kokkos+spack](#)

4. Side note: There exists another cmake-based build system, but relies on a third-party tools [TriBITS](#). Right now this can only be used when Kokkos is build inside [Trilinos](#) (heterogeneous distributed sparse and dense linear algebra package).

Kokkos - initialize / finalize

- Kokkos::initialize / finalize

```
#include <Kokkos_Macros.hpp>
#include <Kokkos_Core.hpp>

int main(int argc, char* argv[]) {
    // default: initialize the host exec space
    // What exactly gets initialized depends on how kokkos
    // was built, i.e. which options was passed to cmake
    Kokkos::initialize(argc, argv);
    ...
    Kokkos::finalize();
}
```

- What's happening inside Kokkos::initialize

- Defines Default Device / DefaultExecutionSpace Default memory space as specified when kokkos itself was built, by order of priority:
Cuda > HIP > SYCL > OpenMPTarget > OpenMP > Threads > HPX > Serial
see header [Kokkos_Macros.hpp](#)
- You can activate several execution spaces (recommended)
- all this information provided at compile time will internally be used inside Kokkos sources as default (hidden) template parameters

Kokkos - initialize / finalize

- Kokkos::initialize / finalize (most of the time OK)

```
#include <Kokkos_Macros.hpp>
#include <Kokkos_Core.hpp>

int main(int argc, char* argv[]) {
    // default: initialize the host exec space
    // What exactly gets initialized depends on how kokkos
    // was built, i.e. which options was passed to cmake
    Kokkos::initialize(argc, argv);
    ...
    Kokkos::finalize();
}
```

- Fine control of initialization:

- **Kokkos::initialize(argc, argv);**

User can change/fix e.g. number OpenMP threads on the application's command line

- This is regular initialization. If available **hwloc** library is available and activated, it provides default hardware locality:

- For OpenMP exec space: number of threads (default is all CPU cores)
NB: usual environment variables (e.g. OMP_NUM_THREADS, GOMP_CPU_AFFINITY) can (of course) also be used
 - Mapping between GPUs and MPI task

Kokkos data Container (1)

Kokkos::View<...> is **multidimensionnal data container** with **hardware adapted memory layout**

- `Kokkos::View<double **> data("data",NX,NY);` : 2D array with sizes known at runtime
- `Kokkos::View<double *[3]> data("data",NX);` : 2D array with first size known at runtime (NX), and second known at compile time (3).
- How do I access data ? *data(i, j) ! à la Fortran*
- **Which memory space ?** By default, the default device memory space !
Want to enforce in which memory space lives the view ? `Kokkos::View<..., Device>`: if a second template parameter is given, Kokkos expects a Device (e.g. Kokkos::OpenMP, Kokkos::Cuda, ...)
- Kokkos::View are **small**, designed as reference to allocated memory buffer
 - View = pointer to data + metadata(array shape, layout, ...)
 - assignment is fast (shallow copy + increment ref counter)¹
- Kokkos::View are designed to be pass by value to a function (**no hard copy**).

¹ NB: same behaviour as in python for example

Kokkos data Container (2)

- Concept of **memory layout**:
- **Memory layout is crucial for performance:**
 - **LayoutLeft:** $data(i, j, k)$ uses linearized index as $i + NX * j + NX * NY * k$ (column-major order)
 - **LayoutRight:** $data(i, j, k)$ uses linearized index as $k + NZ * j + NZ * NY * i$ (row-major order)
- **Kokkos::View<int**, Kokkos::OpenMP> defaults with LayoutRight;** a single thread access contiguous entries of the array. Better for cache and avoid sharing cache lines between threads.
- **Kokkos::View<int**, Kokkos::Cuda> defaults LayoutLeft** so that consecutive threads in the same warp access consecutive entries in memory; try to ensure memory coalescence constraint
- You can if you like, still enforce memory layout yourself (or just use 1D Views, and compute index yourself);
We will see the 2 possibilities with the miniApp on the Fisher equation

Kokkos data Container (3)

- `Kokkos::View<...>` are reference-counted
- **shallow copy** is default behavior

```
Kokkos::View<int *> a("a",10);
Kokkos::View<int *> b("b",10);
a = b; // a now points to b (ref counter incremented by 1)
// a destructor (memory deallocation) only actually happen
// when ref counter reaches zero.
```

- **Deep copy** must be explicit:

```
Kokkos::deep_copy(dest,src);
```

- **Usefull when copying data from a memory space to another**
e.g. **from HostSpace to CudaSpace** replacing `cudaMemcpy`
⇒ one API for all targets
- When `dest` and `src` are in the same memory space, it does nothing ! (usefull for portability, see example in miniapps later)

Kokkos compute Kernels - parallel dispatch (1)

- 3 types of parallel dispatch
 - Kokkos::parallel_for
 - Kokkos::parallel_reduce
 - Kokkos::parallel_scan
- A dispatch needs as input
 - **an execution policy:** e.g. a range (can simply be an integer), team of threads, ...
 - **a body:** specified as a lambda function or a functor
- Very important: launching a kernel (thread dispatching) is by default asynchronous

Kokkos compute Kernels - parallel dispatch (2)

How to specify a compute kernel in Kokkos ?

1. Use Lambda functions.

NB: a lambda in c++11 is an unnamed function object capable of capturing variables in scope.

```
// Note: here we use the simplest way to specify an execution policy
// i.e. the first parameter (100)
Kokkos::parallel_for (100, KOKKOS_LAMBDA (const int i) {
    data(i) = 2*i;
});

// is equivalent to the following serial code
for(int i = 0; i<100; ++i) {
    data[i] = 2*i;
}
```

KOKKOS_LAMBDA is a preprocessor macro specifying the **capture close**

- by default **KOKKOS_LAMBDA** is aliased to **[=]** to capture variables of surrounding scope **by value**
- **KOKKOS_LAMBDA** has a special definition if CUDA is enabled

Kokkos compute Kernels - parallel dispatch (2)

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    data(i) = 2*i;
});

// is equivalent to the following serial code
for(int i = 0; i<100; ++i) {
    data[i] = 2*i;
}
```

Using lambda's means 2 things in 1:

- define the computation body (lambda func)
- launch computation.

Kokkos compute Kernels - parallel dispatch (3)

How to specify a compute kernel in Kokkos ?

2. Use a C++ functor class.

A functor is a class containing a function to execute in parallel, usually it is an operator ()

```
class FunctorType {
public:
    // constructor : pass data
    FunctorType(Kokkos::View<...> data);

    KOKKOS_INLINE_FUNCTION
    void operator() ( const int i ) const
    { data(i) = 2*i; };
};

...
Kokkos::View<int *> some_data("some_data",100);
FunctorType func(some_data); // create a functor instance
Kokkos::parallel_for (100, func); // launch computation
```

- KOKKOS_INLINE_FUNCTION is a macro with different meaning depending on target (e.g. it contains __device__ for cuda)

Kokkos compute Kernels - parallel dispatch (4)

Notes on macros defined in `core/src/Kokkos_Macros.hpp`

- `KOKKOS_LAMBA` is a macro which provides a compiler-portable way of specifying a lambda function with **capture-by-value closure**.
 - `KOKKOS_LAMBA` must be used at the most outer parallel loop; inside a lambda one can call another lambda
- `KOKKOS_INLINE_FUNCTION void operator() (...) const;`
this macro helps providing the necessary compiler specific *decorators*, e.g. `--device--` for Cuda to make sure the body can be turned into a Cuda kernel.
 - macro `KOKKOS_INLINE_FUNCTION` must be applied to any function call inside a parallel loop

Kokkos compute Kernels - parallel dispatch (5)

Lambda or Functor: which one to use in Kokkos ? Both !

1. Use Lambda functions.

- easy way for small compute kernels
- For GPU, requires Cuda 7.5 (8.0 is current and latest CUDA version)

2. Use a C++ functor class.

- More flexible, allow to design more complex kernels

Kokkos compute Kernels - parallel dispatch (6)

About Kokkos::parallel_reduce with lambda

- As for `parallel_for`, loop body can be specified as a **lambda**, or a **functor**; here is the lambda way when reduce operation is `sum`:

```
// - local_sum is a temporary variable to transfer intermediate result
// between threads (or block of threads)
// - sum contains the final reduced result
Kokkos::parallel_reduce (100,
    KOKKOS_LAMBDA (const int i, int &local_sum) {
        local_sum += data(i);
    },
    sum);
```

- Important note: using `parallel_reduce` with lambda is only really usefull if the reduce operation '+'
- If the reduce operation is something else, you need to specify:
 - how the local result is initialized (default 0)
 - how the different intermediate results are *joined*

Kokkos compute Kernels - parallel dispatch (7)

About Kokkos::parallel_reduce with a functor

- Kokkos supplies a default init / join operator which is operator+
- If the reduce operator is not trivial (i.e. not a sum) ⇒ you need to define methods init and join

```
class ReduceFunctor {  
public:  
    // declare a constructor ...  
    KOKKOS_INLINE_FUNCTION void  
    operator() (const int i, data_t &update) const {...}  
  
    // How to join/combine intermediate reduce from different threads  
    KOKKOS_INLINE_FUNCTION void  
    join(volatile data_t &dst, const volatile data_t &src) const {...}  
  
    // how each thread initializes its reduce result  
    KOKKOS_INLINE_FUNCTION void  
    init(const volatile data_t &dst) const {...}  
}
```

This is useful when the reduced variable is complex (e.g. a multi-field structure)

Kokkos compute Kernels - parallel dispatch (8)

Parallel dispatch - execution policy

- Remember that an execution policy specifies **how** a parallel dispatch is done by the device
- Range policy:** from...to
no prescription of order of execution nor concurrency; allows to adapt to the actual hardware; e.g. a GPU has some level of hardware parallelism (Streaming Multiprocessor) and some levels of concurrency (warps and block of threads).
- Multidimensional range:** still experimental (as of January 2017), mapping a higher than 1D range of iteration.

```
// create the MDrangePolicy object
using namespace Kokkos::Experimental;
using range_type = MDRangePolicy< Rank<2>, Kokkos::IndexType<int> >;
range_type range( {0,0}, {N0,N1} );

// use a special multidimensional parallel for launcher
md_parallel_for(range, functor);
```

Kokkos compute Kernels - parallel dispatch (9)

Parallel dispatch - execution policy

- **Team policy:** for hierarchical parallelism
 - threads team
 - threads inside a team
 - vector lanes
- ```
// Using default execution space and launching
// a league with league_size teams with team_size threads each
Kokkos::TeamPolicy <>
 policy(league_size , team_size);
```

equivalent to launching in CUDA a 1D grid of 1D blocks of threads.

Team scratch pad memory  $\Longleftrightarrow$  CUDA shared memory

- Lambda interface changed:

```
KOKKOS_LAMBDA (const team_member& thread) { ...};
```

team\_member is a structure (aliased to

Kokkos::TeamPolicy<>::member\_type)

## Kokkos compute Kernels - parallel dispatch (10)

### Parallel dispatch - execution policy

- **Team policy:** for **hierarchical parallelism**
- **team\_member** is a structure equipped with
  - `league_size()` : return number of teams (of threads)
  - `league_rank()` : return team id (of current thread)
  - `team_size()` : return number of threads (per team)
  - `team_rank()` : return thread id (of current thread)
- Can I synchronize threads ?  
Yes, but only threads inside a team (same semantics as in CUDA with  
`--syncthreads();`  
⇒ `team_barrier()`

## Kokkos compute Kernels - parallel dispatch (11)

### Team policy: for hierarchical parallelism

```
// with the team policy you need to map a thread to an iteration id
KOKKOS_INLINE_FUNCTION
void operator() (const team_member & thread) {
 // example of data/iteration mapping (similar to CUDA)
 int i = thread.team_rank() +
 thread.league_rank() * thread.team_size();
 data(i) = ... ;
}
```

this very similar to CUDA:

```
// inside a CUDA kernel, using built-in variables
// threadIdx and blockIdx
int index = threadIdx.x + blockIdx.x * blockDim.x;
```

## Kokkos compute Kernels - parallel dispatch (12)

### Team policy: for nested parallelism

```
// within a parallel functor with team policy
// you can call another parallel_for / reduce / ...
KOKKOS_INLINE_FUNCTION
void operator() (const team_member & thread) {
 // do something (all threads of all teams participate)
 do_something();

 // then parallelize a loop over all threads of a team
 // each team is executing a loop of 200 iterations
 // the 200 iterations are splitted over the thread of current team
 // the total number of iterations is 200 * number of teams
 Kokkos::parallel_for(Kokkos::TeamThreadRange(thread,200),
 KOKKOS_LAMBDA (const int& i) {
 ...
 });
}
```

## Kokkos compute Kernels - parallel dispatch (13)

### Hierarchical parallelism (advanced)

- OpenMP: League of Teams of Threads
- Cuda: Grid of Blocks of Threads
- Experimental features: task parallelism
  - see slides by C. Edwards at GTC2016 [2016-04-GTC-Kokkos-Task.pdf](#)
  - [Kokkos Task DAG capabilities](#)
  - Example application: [Task Parallel Incomplete Cholesky Factorization using 2D Partitioned-Block Layout](#)

## Kokkos compute Kernels - Advanced items

### SIMD / Vectorization

The following reference give details / best practices to obtain carefully written kernels for portable SIMD vectorization:

<http://www.sci.utah.edu/publications/Sun2016a/ESPM2Dan-sunderland.pdf>

- Kokkos::subview ⇒ allow to extract a *view*

```
// assume data is a 3d Kokkos::View
// slice is a 1d sub view : column at (i,j)
auto slice = subview(data, i, j, ALL());
```

This is usefull for SIMD, auto vectorization, it helps the compiler understand we are accessing memory with a stride 1 (assuming layout right, which is the default for OpenMP device).

## Kokkos - cmake integration (1)

- Why Cmake ?
  - cmake is supported by kokkos
  - easy to integrate and configure (versus e.g. old autotools, versus regular Makefile): need to handle the architecture flags combinatorics
- User application top-level cmake can be as small as 7 lines

```
cmake_minimum_required(VERSION 3.16)
project(myproject CXX)

C++11 is for Kokkos
set(CMAKE_CXX_STANDARD 14)
set(CMAKE_CXX_EXTENSIONS OFF)

first build kokkos
not recommended, but ok for demo
add_subdirectory(external/kokkos)

build the user sources
add_executable(my_exe PRIVATE main.cpp)
target_link_library(my_exe PRIVATE Kokkos::kokkos)
```

## Kokkos - cmake integration (2)

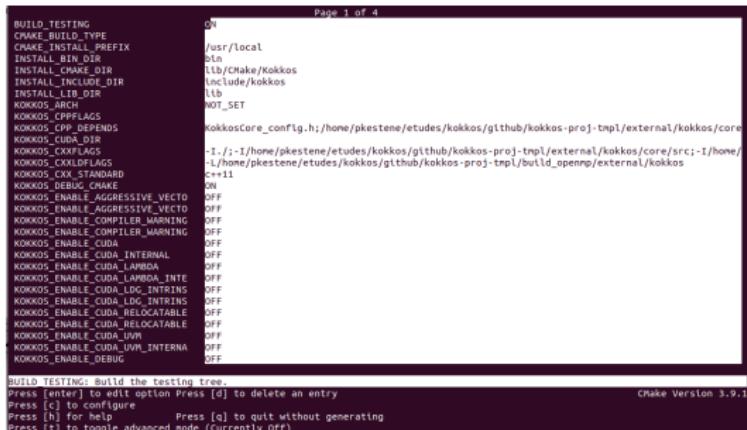
### List of important kokkos-related **cmake variables**

- **KOKKOS\_ENABLE\_OPENMP**, **KOKKOS\_ENABLE\_CUDA**,... ⇒ which execution space are enabled (multiple possible)
- **KOKKOS\_ARCH** (bold values are relevant for ouessant), will trigger relevant arch flags (complete list avail. from `Makefile.kokkos`)

|             |                                                                                                                                                                |
|-------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------|
| # Intel:    | KNC,KNL,SNB,HSW,BDW,SKX                                                                                                                                        |
| # NVIDIA:   | Kepler,Kepler30,Kepler32,Kepler35, <b>Kepler37</b> ,Maxwell,<br>Maxwell50,Maxwell52,Maxwell53, <b>Pascal60</b> ,Pascal61,<br>Volta70,Volta72,Turing75,Ampere80 |
| # ARM:      | ARMv80,ARMv81,ARMv8-ThunderX,ARMv8-TX2                                                                                                                         |
| # IBM:      | BGQ,Power7, <b>Power8</b> ,Power9                                                                                                                              |
| # AMD-GPUS: | Kaveri,Carrizo,Fiji,Vega                                                                                                                                       |
| # AMD-CPUS: | AMDAVX,Ryzen,Epyc                                                                                                                                              |

## Kokkos - cmake integration (3)

- curse gui interface: `ccmake`



The screenshot shows the ccmake configuration interface for the Kokkos project. It displays a list of build options with their current values:

| Option                          | Value                       |
|---------------------------------|-----------------------------|
| BUILD_TESTING                   | ON                          |
| CMAKE_BUILD_TYPE                | RELEASE                     |
| CMAKE_CXX_STANDARD              | PREFER                      |
| INSTALL_BIN_DIR                 | /usr/local/bin              |
| INSTALL_CMAKE_DIR               | /usr/local/lib/cmake/Kokkos |
| INSTALL_INCLUDE_DIR             | /usr/local/include/kokkos   |
| INSTALL_LIB_DIR                 | /usr/local/lib              |
| KOKKOS_CXX_STANDARD             | NOT_SET                     |
| KOKKOS_CPPFLAGS                 |                             |
| KOKKOS_CPP_DEPENDS              |                             |
| KOKKOS_CUDA_DIR                 |                             |
| KOKKOS_CXXFLAGS                 |                             |
| KOKKOS_CXXLDFLAGS               |                             |
| KOKKOS_CXX_STDLIB               | -stdlib=libc++              |
| KOKKOS_CXX_STDLIB_CXX           | CXX11                       |
| KOKKOS_ENABLE_AGGRESSIVE        | ON                          |
| KOKKOS_ENABLE_AGGRESSIVE_VECTO  | OFF                         |
| KOKKOS_ENABLE_AGGRESSIVE_VECTO  | OFF                         |
| KOKKOS_ENABLE_COMPILER_WARNING  | OFF                         |
| KOKKOS_ENABLE_COMPILER_WARNING  | OFF                         |
| KOKKOS_ENABLE_CUDA              | OFF                         |
| KOKKOS_ENABLE_CUDA_INTERNAL     | OFF                         |
| KOKKOS_ENABLE_CUDA_LAMBDA       | OFF                         |
| KOKKOS_ENABLE_CUDA_LAMBDA_INTE  | OFF                         |
| KOKKOS_ENABLE_CUDA_LDG_INTRINS  | OFF                         |
| KOKKOS_ENABLE_CUDA_LDG_INTRINS  | OFF                         |
| KOKKOS_ENABLE_CUDA_RELLOCATABLE | OFF                         |
| KOKKOS_ENABLE_CUDA_RELLOCATABLE | OFF                         |
| KOKKOS_ENABLE_CUDA_UVM          | OFF                         |
| KOKKOS_ENABLE_CUDA_UVM_INTE     | OFF                         |
| KOKKOS_ENABLE_DEBUG             | OFF                         |

At the bottom of the interface, there is a status bar with the message "BUILD TESTING ON in the testing tree." and a help message: "Press [e] to edit option Press [d] to delete an entry Press [c] to configure Press [h] for help Press [q] to quit without generating Press [t] to toggle advanced mode (Currently Off)".

- command line interface : `cmake mkdir build_openmp; cd build_openmp; ccmake -DKOKKOS_ENABLE_OPENMP ..`
- How to build ? for OpenMP / CUDA ?

# A template starter project

## Activity: Use the template cmake / kokkos project

- Clone the template project:

```
git clone --recursive https://github.com/pkestene/kokkos-proj-tmpl.git
```

- Build the sample application (saxpy): use ccmake interface to setup the Kokkos OpenMP target; then try to setup the CUDA target (for arch Turing75)

```
mkdir build_openmp; cd build_openmp; ccmake ..
set KOKKOS_ENABLE_OPENMP to ON
make
```

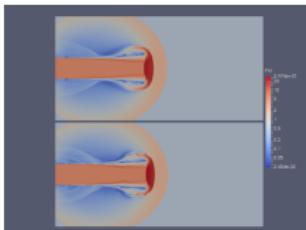
- Build the sample application (saxpy): repeat as above to setup the Kokkos CUDA target (for arch Kepler37)

```
don't forget to set environment variable CXX
export CXX="full path to nvcc_wrapper"
mkdir build_cuda_turing75; cd build_openmp; ccmake ..
set KOKKOS_ENABLE_CUDA to ON; set KOKKOS_ARCH
make
```

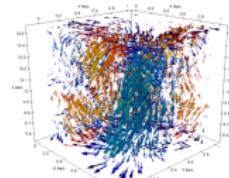
- Try to add another executable; e.g. copy of the tutorial 01\_hello\_world

# Scientific software devel. at MDLS using Kokkos

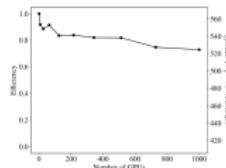
- since 2016: R&D using MPI+Kokkos  
mini-app EulerKokkos  $\Rightarrow$  ARK (**high/low Mach flow with well-balanced gravity**) by T. Padoleau, P. Tremblin  
(DRF/MDLS), S. Kokh (DES/STMF), ARK-RT (Radiative transfert)
- 2018: LBM\_Saclay with A. Cartalade and A. Genty  
(DES/STMF)  
PhD: W. Verdier, T. Boutin: Two-phase flow  
(Navier-Stokes + phase fields models) with phase change  
using **Lattice Boltzmann methods** for studying demixing  
process in glasses, dissolution in porous media.
- 2017-2018: ppkMHD MPI+Kokkos implementation of  
high order **spectral difference method** (SDM)



(left) ppkMHD (MPI+Kokkos: high Mach ( $M=27$ ) jet  
(right) LBM\_Saclay (MPI+Kokkos): film boiling (2019, Verdier, STMF)



ARK Rayleigh-Benard instability (2019,  
Padoleau, MDLS)



ARK GPU weak-scaling,  $4960^3$  (2019,  
Daley-Yates, MDLS, Jean Zay/IDRIS)

# Prototyping adaptive mesh refinement with Kokkos

- At CEA/DRF/IRFU

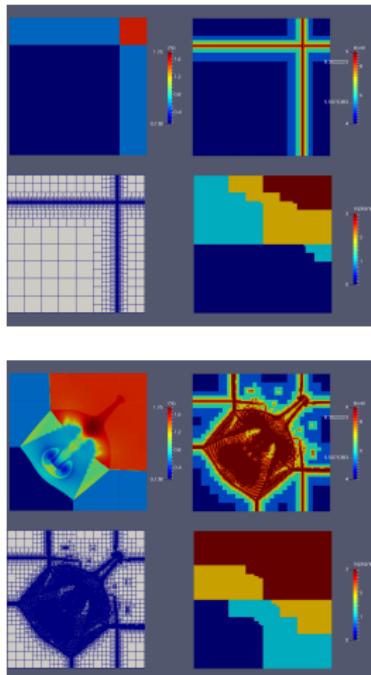
(A. Durocher, M. Delorme) :

**Dyablo = A C++ software platform  
for octree-based AMR CFD  
applications** using external libraries:

- (PABLO) for distributed mesh management and AMR algorithms
- Kokkos for shared mem. parallelism (CPU/GPU)

- Mini-app focused on single-node AMR running entirely on device (GPU) written in Kokkos for LBM applications

- E. Stavropoulos Vasilakis  
(CEA/DES/STMF), started **02/2021**,  
Lattice Boltzmann numerical scheme implementation



code CanoP (p4est)

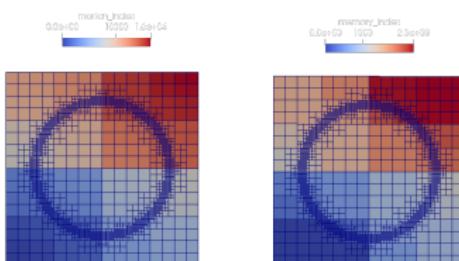
# Kokkos + AMR = khamr

- Sand box / testing ideas of generic multi-architecture AMR
- testing sorting algorithmes with Kokkos, bucket sort, ...
- testing Morton index and data containers (encode/decode, use level/tree id)

KOKKOS\_INLINE\_FUNCTION

```
uint64_t morton_key(const int ix, const int iy, const int iz)
{
 uint64_t key = 0;
 key |= splitBy3<3>(ix) | splitBy3<3>(iy) << 1 | splitBy3<3>(iz) << 2;
 return key;
} // morton_key - 3d
```

- testing parallel hash tables



## Kokkos for Cuda users

From a pure software engineering point of view, how does **Kokkos** manage to turn a **pure C++ functor** into a **CUDA kernel** ?

1. entry point of parallel computation is through `parallel_for` (function call, templated by execution policy, functor, ...)

```
// parallel_for is defined in
// core/src/Kokkos_Parallel.hpp : line 200
template< class FunctorType >
inline
void parallel_for(const size_t work_count
 , const FunctorType& functor
 , const std::string& str = ""
)
{
 // ...
 Impl::ParallelFor< FunctorType , policy >
 closure(functor , policy(0,work_count));
 // ...
}
```

## Kokkos for Cuda users

2. closure is an instance of the **driver** class Kokkos::Impl::ParallelFor; the precise object type created is off course Kokkos-backend dependent
3. If CUDA backend is activated, the instantiated class Kokkos::Impl::ParallelFor is defined in Cuda/Kokkos\_Cuda\_Parallel.hpp; there are multiple specialization for the different execution policies (Range, multi-dimensional range, team policy, ...); e.g. for range

```
template< class FunctorType , class ... Traits >
class ParallelFor< FunctorType
 , Kokkos::RangePolicy< Traits ... >
 , Kokkos::Cuda
>
{
 // this is where for a given iteration id, the functor is called
 // kind of generic cuda kernel work definition
 inline __device__ void operator()(void) const { ... };

 // this is where the actual CUDA kernel run time config
 // is setup : block and grid dimension
 // then create a CudaParallelLaunch object
 inline void execute() const { ... };
}
```

## Kokkos for Cuda users

4. when `closure.execute()` is called, an object `CudaParallelLaunch` is created
5. struct `CudaParallelLaunch` contains only a constructor, which only purpose is to actually launch the CUDA kernel (using the `<<< ... >>>` syntax)
6. Copy closure (driver instance) to GPU memory (either constant, local or global) using Cuda API (e.g `cudaMemcpyToSymbolAsync` to copy constant memory space)
7. finally the actual generated cuda kernel, using one of the static functions defined (e.g. `cuda_parallel_launch_constant_memory`)